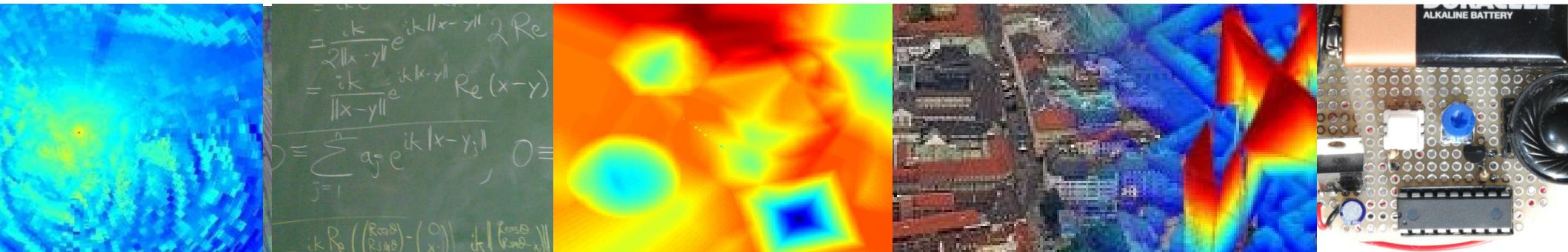


# Topological Features *into* Complex Models



Michael Robinson



# Acknowledgments

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- Students:
  - Zander Memon (AU)
  - Harry Pham (AU)
  - Trixie Southwood (AU)
  - Maxwell Gualtieri (Northwestern)
- Collaborators:
  - Donna Dietz (AU)
  - Brian DiZio (NUWC Newport)
  - Michael Postol
  - Michael Szulczewksi (MITRE)
  - James Thorson (NOAA)
- Funding: Jason Chaytor (ONR) and PNNL KBASE
- Main references:

<https://arxiv.org/abs/2511.04603>

<https://github.com/kb1dds/netlist-sheaf>

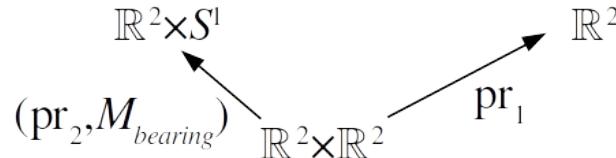
Thorson, J. T., Andrews, A. G., Essington, T., & Large, S. (2024). Dynamic structural equation models synthesize ecosystem dynamics constrained by ecological mechanisms. *Methods in Ecology and Evolution* 15(4): 744-755. <https://doi.org/10.1111/2041-210X.14289>



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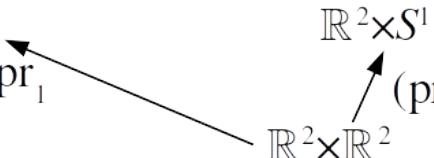
# Systems of systems are diagrams...

## Sensor 1 position, Bearing



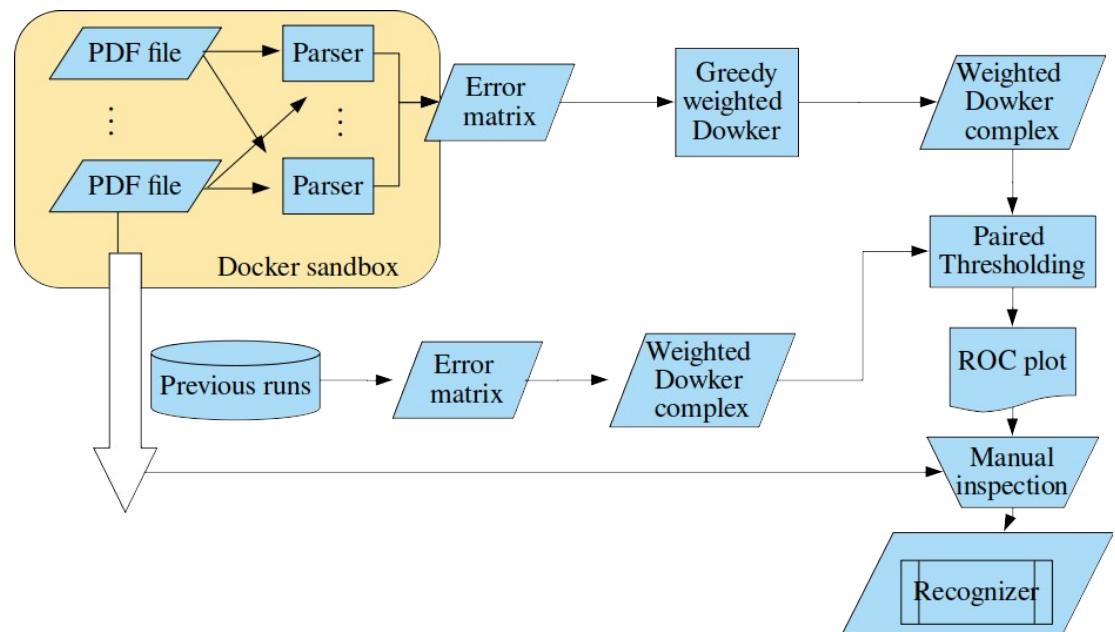
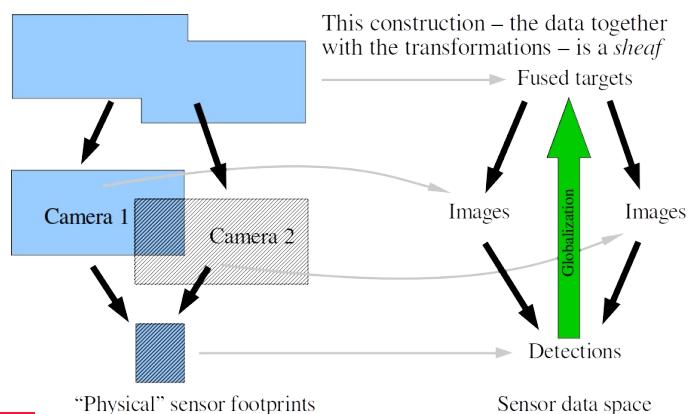
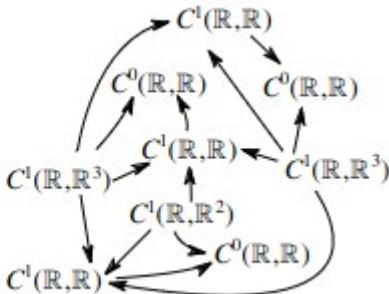
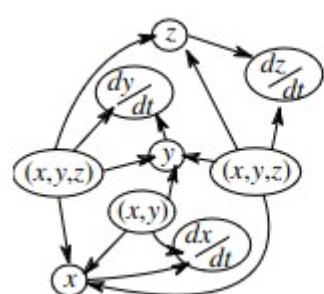
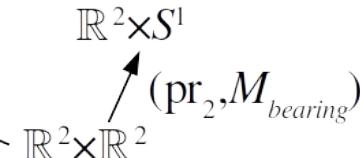
Fox position, Sensor 1 position

## Fox position



Fox position, Sensor 2 position

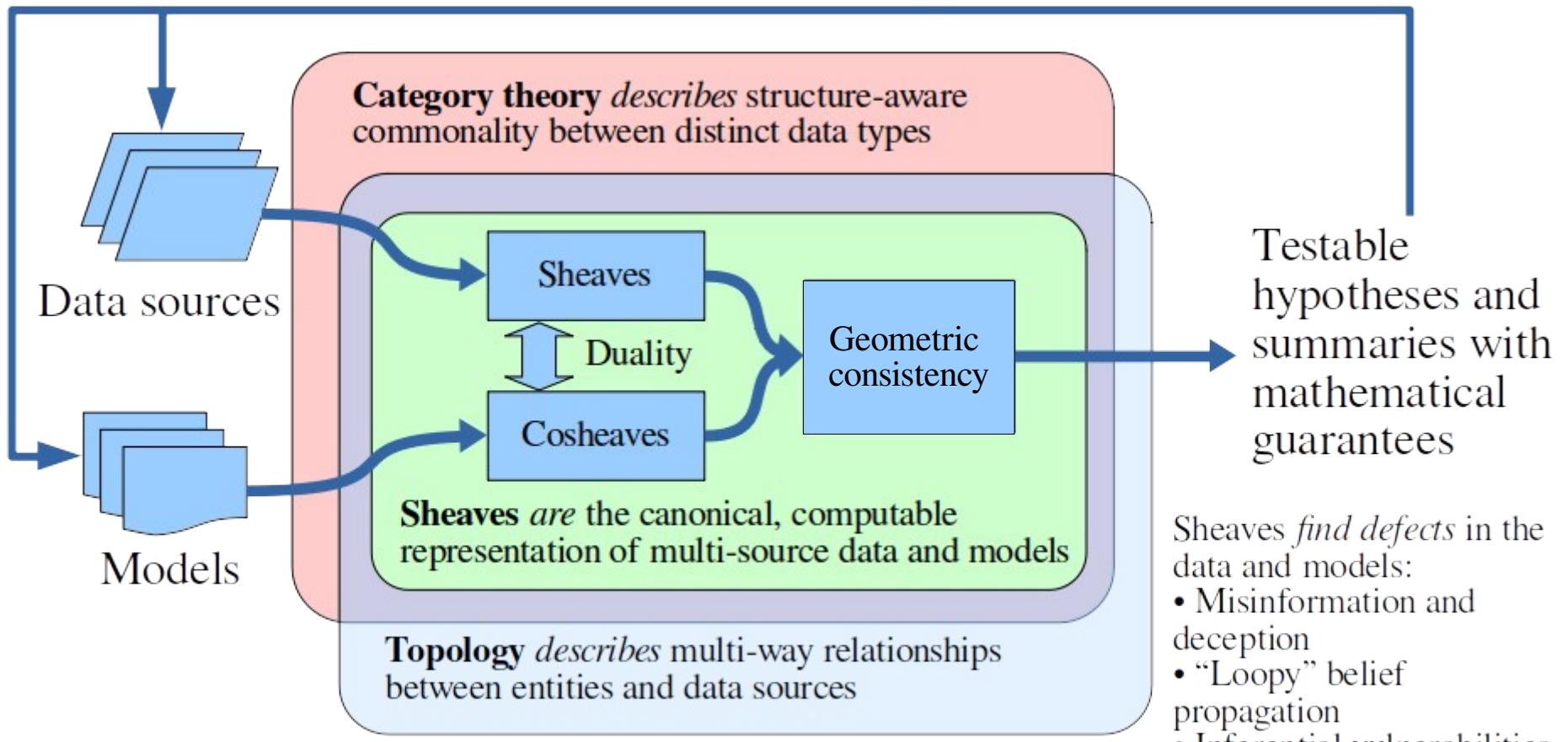
## Sensor 2 position, Bearing



... so use mathematics suited to diagrams:  
*topology, sheaves, and categories*

# ... and the correct mathematical tools yield performance guarantees

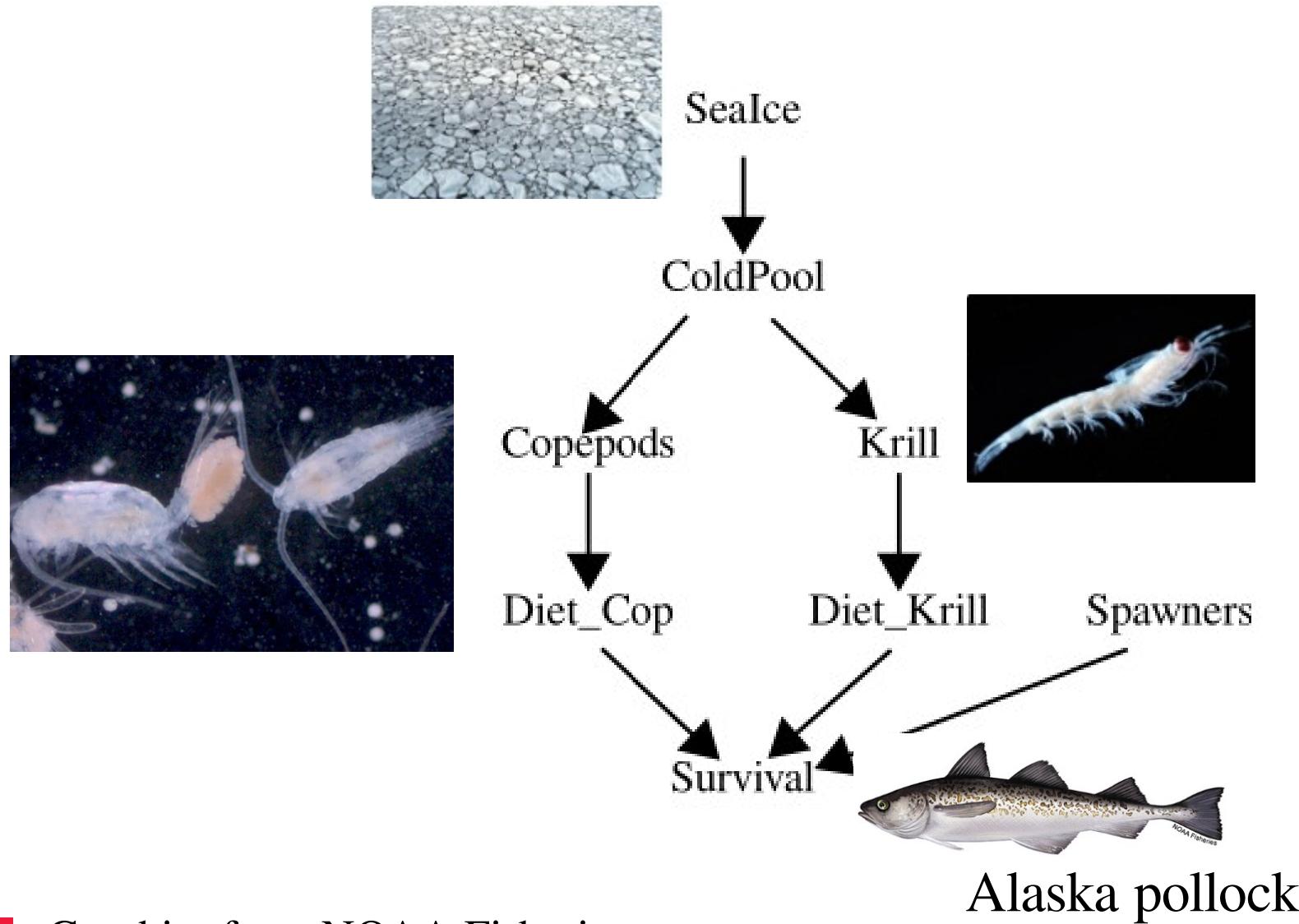
Sheaf-based tools *close the loop* on data science



# Translating models into sheaves



# Dynamic Structural Equation Model



Graphics from NOAA Fisheries

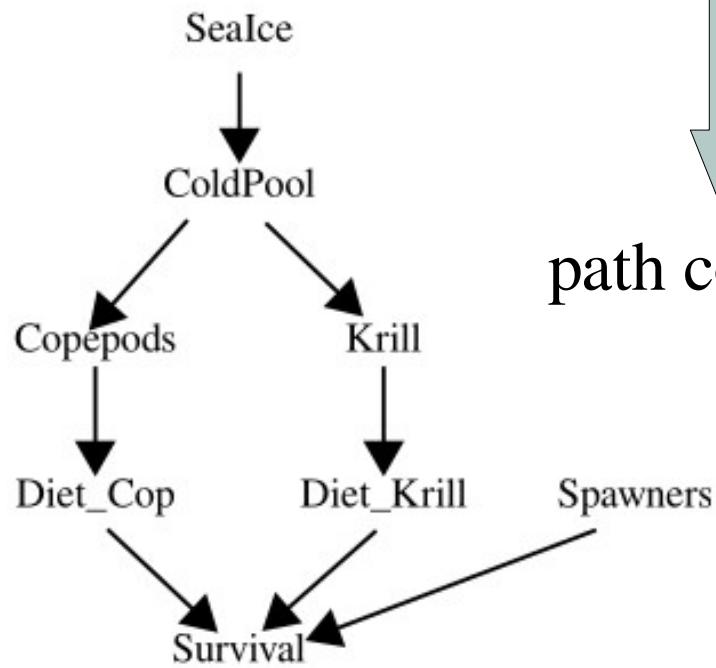
James Thorson

Michael Szulczewski

Michael Robinson

# Dynamic Structural Equation Model

$$\frac{dx_k(\tau - t_\ell)}{d\tau} = \sum_{i=1}^J \sum_{j=1}^T \gamma_{k,\ell,i,j} x_i(\tau - t_j)$$



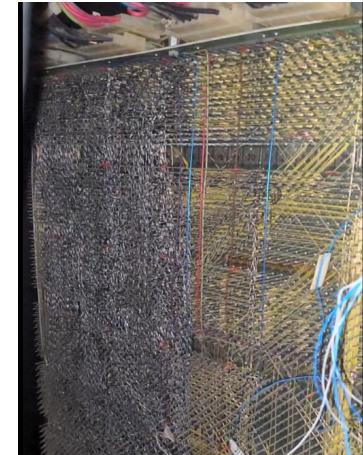
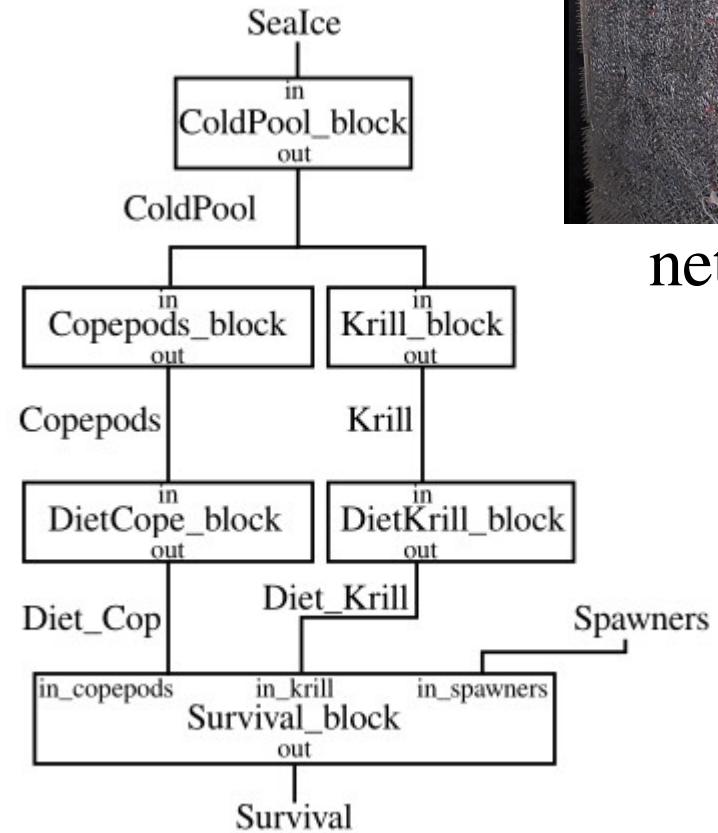
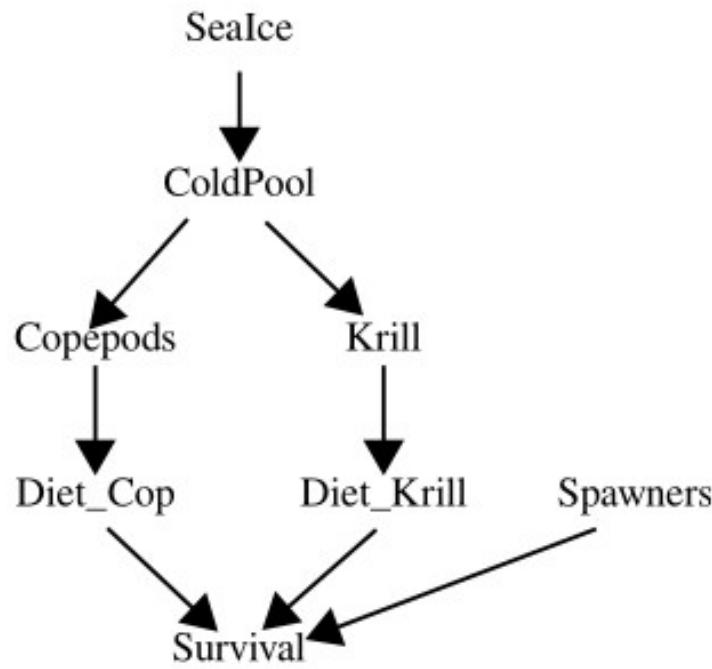
path coefficients  $\gamma$  are directed edges

variables  $x_i$  are nodes

Time lags  $t_j$  not shown

# DSEM → netlist (circuit diagram)

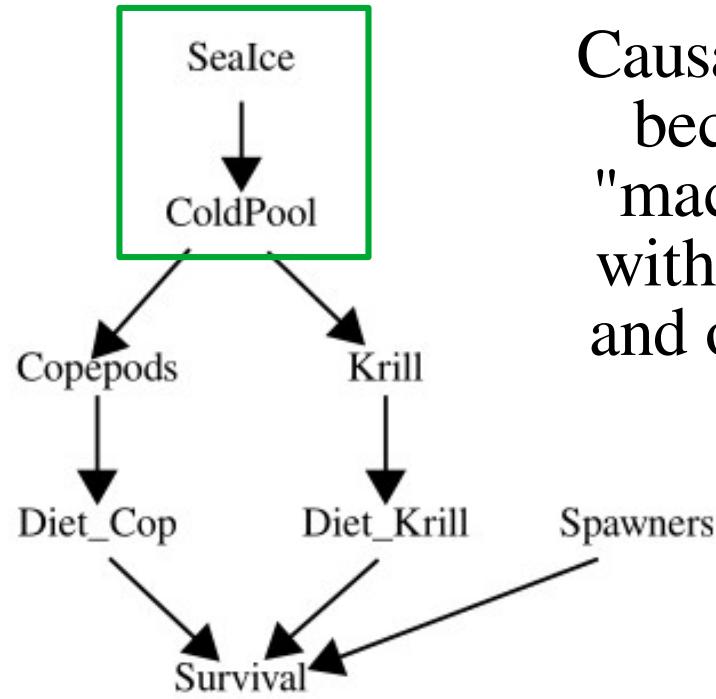
$$\frac{dx_k(\tau - t_\ell)}{d\tau} = \sum_{i=1}^J \sum_{j=1}^T \gamma_{k,\ell,i,j} x_i(\tau - t_j)$$



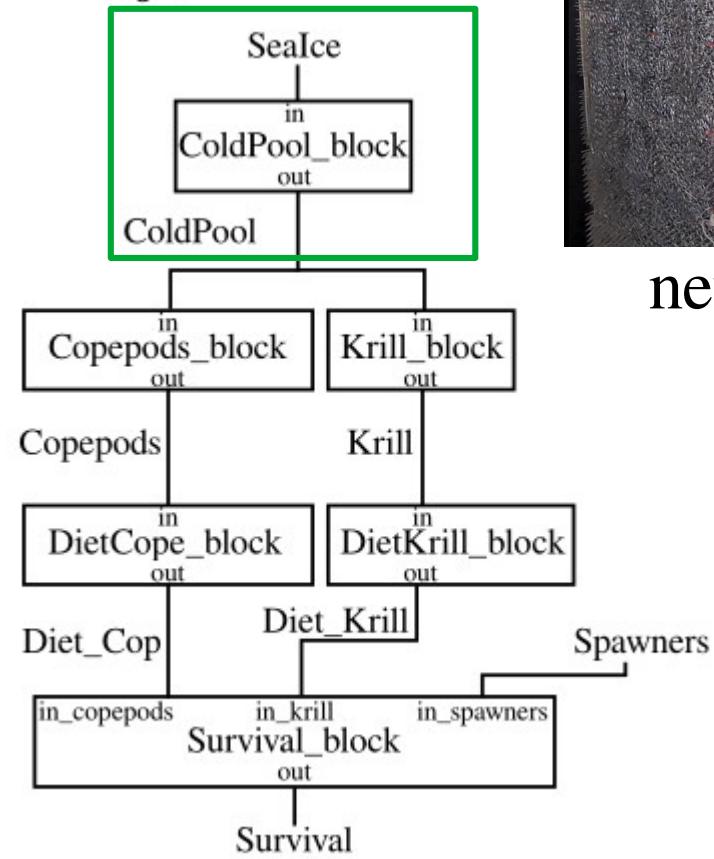
netlists!

# DSEM $\rightarrow$ netlist (circuit diagram)

$$\frac{dx_k(\tau - t_\ell)}{d\tau} = \sum_{i=1}^J \sum_{j=1}^T \gamma_{k,\ell,i,j} x_i(\tau - t_j)$$



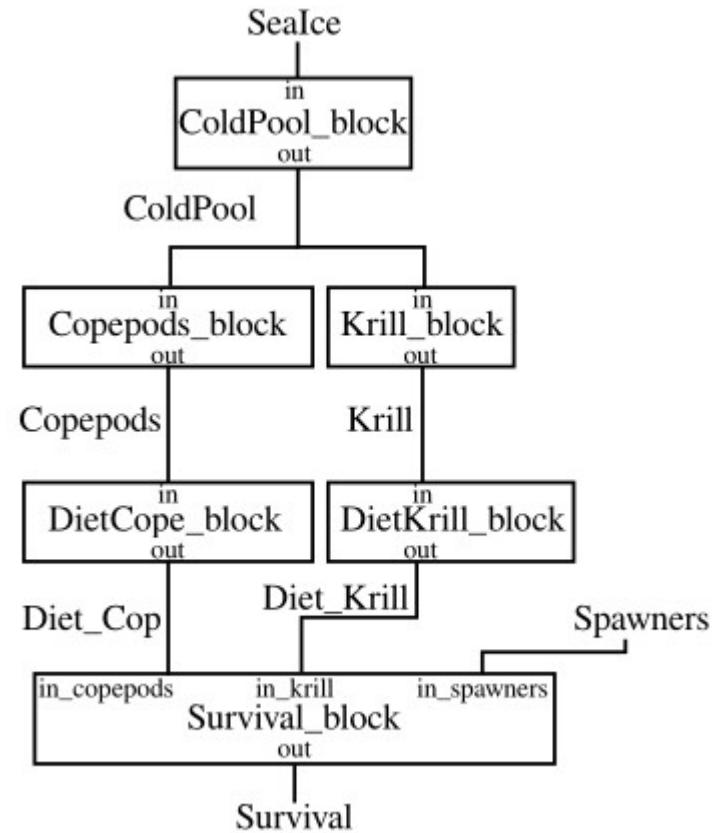
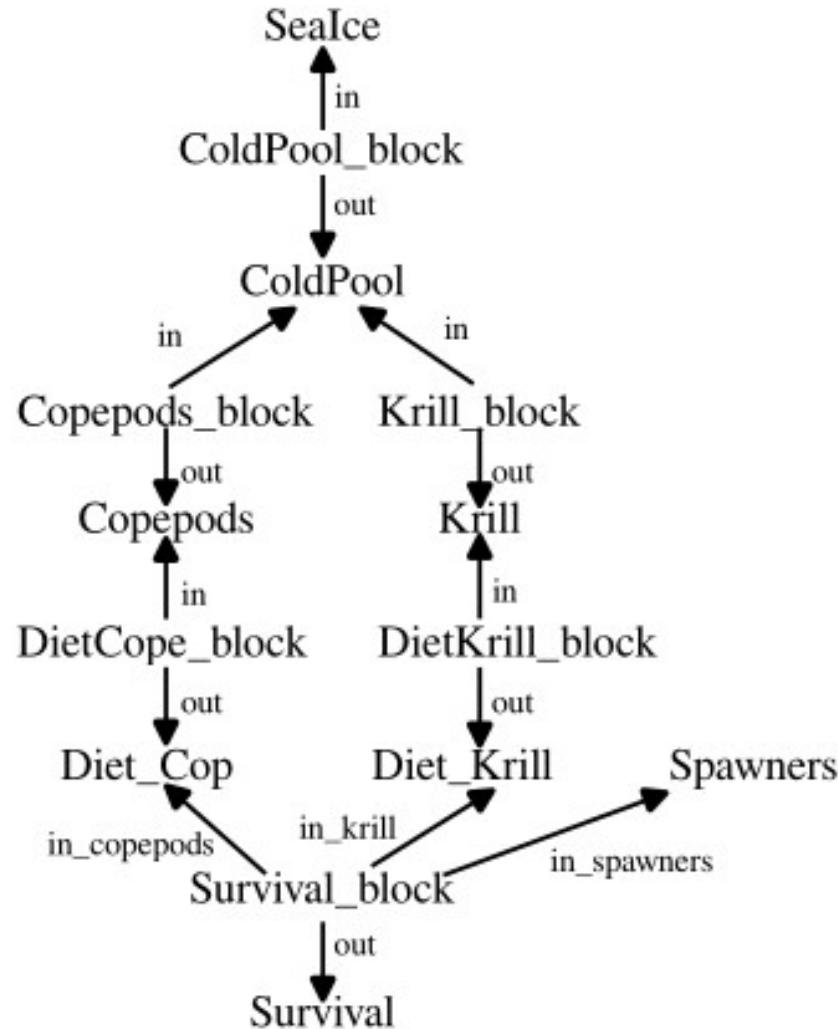
Causal paths become "machines" with inputs and outputs



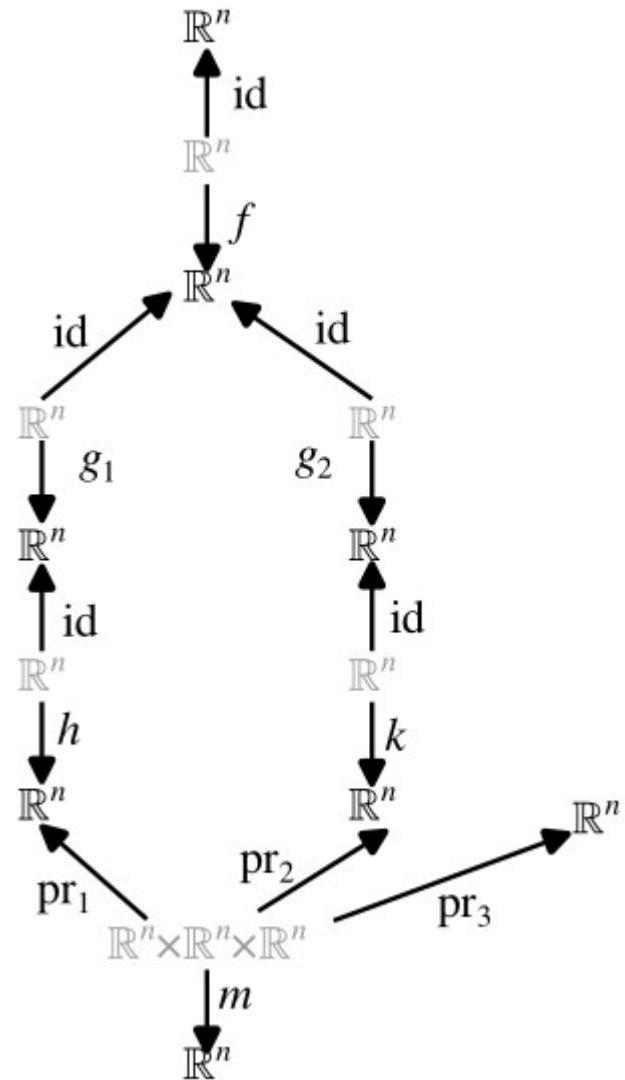
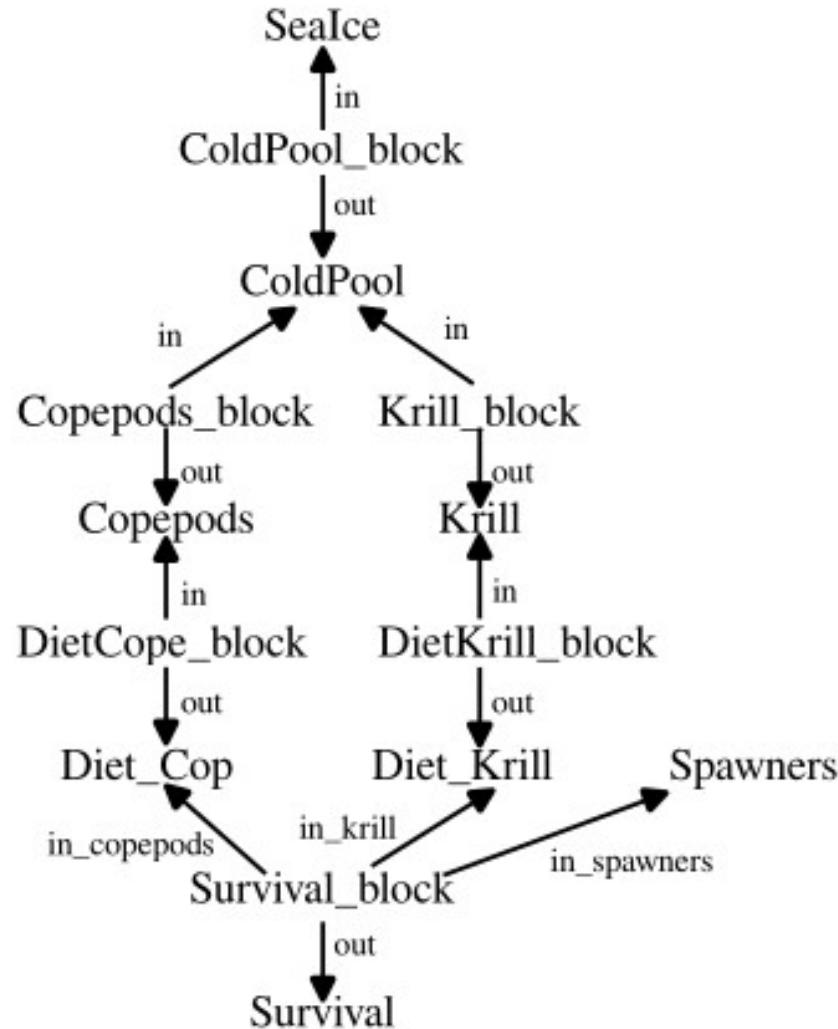
netlists!



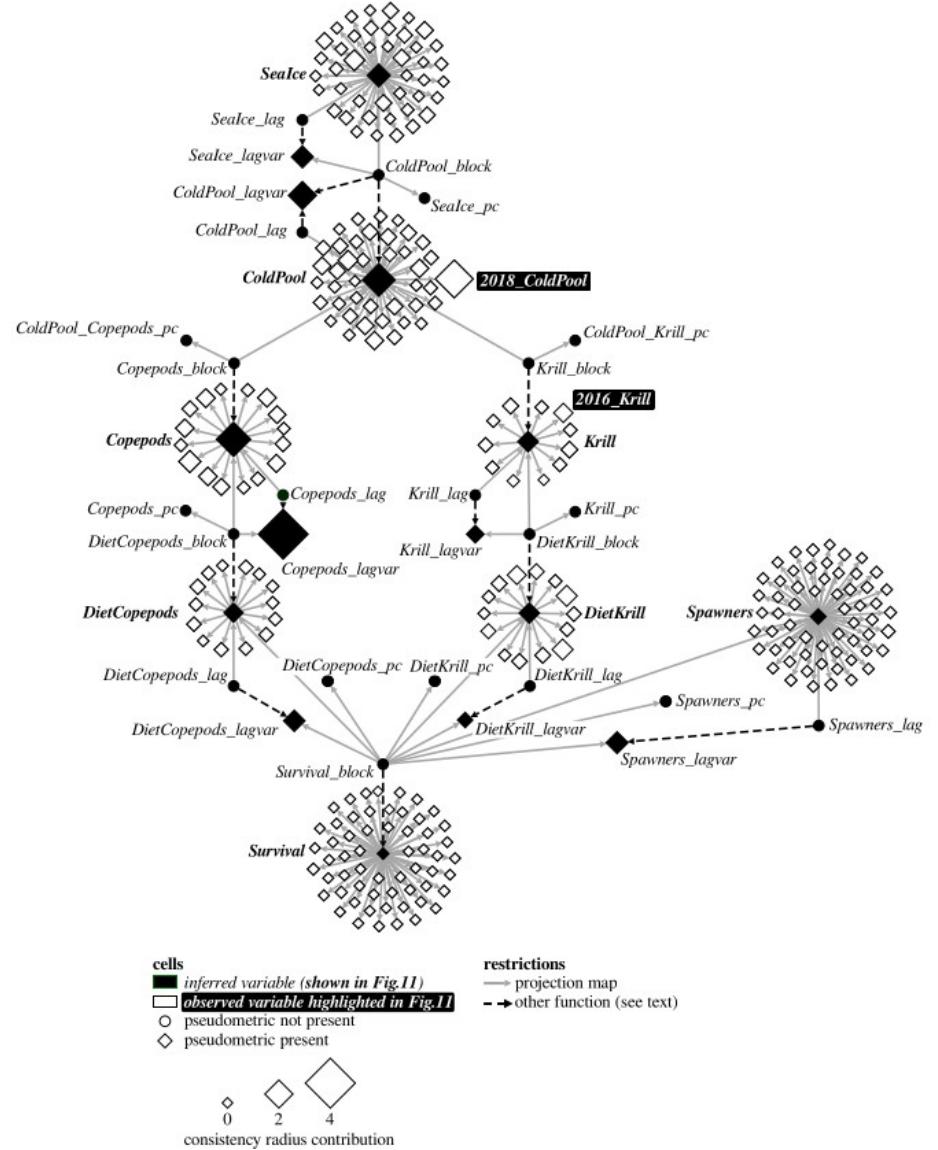
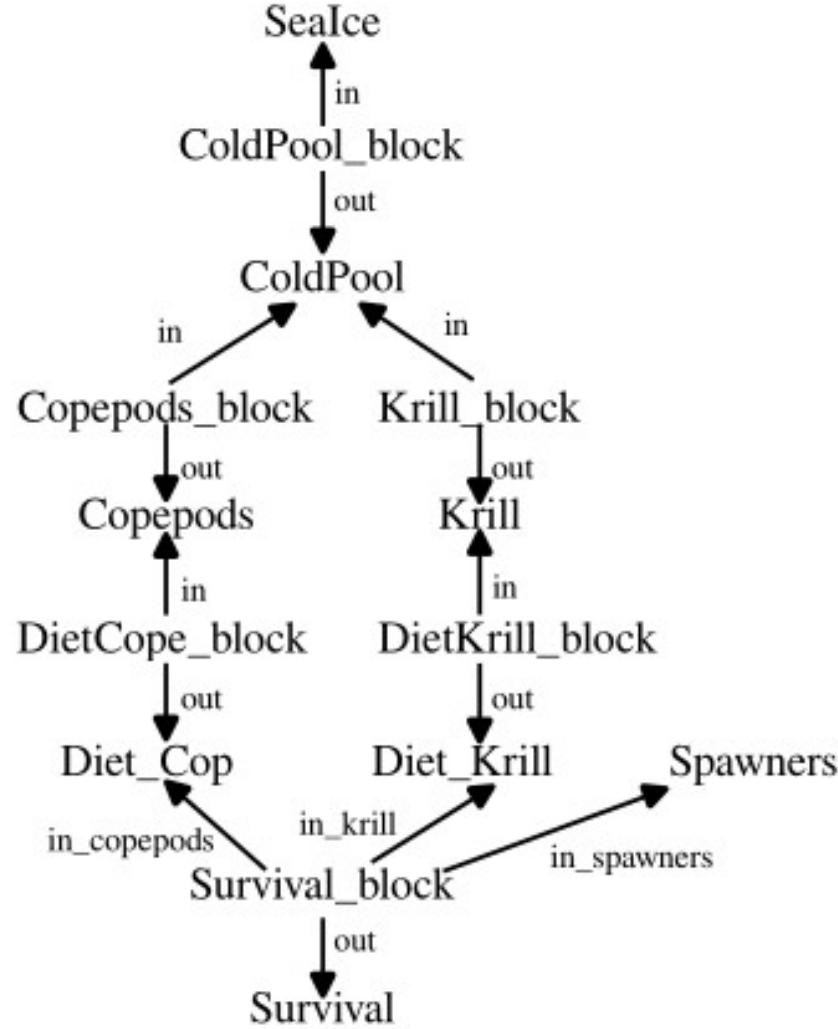
# Netlist incidence graph



# Incidence graph to sheaf

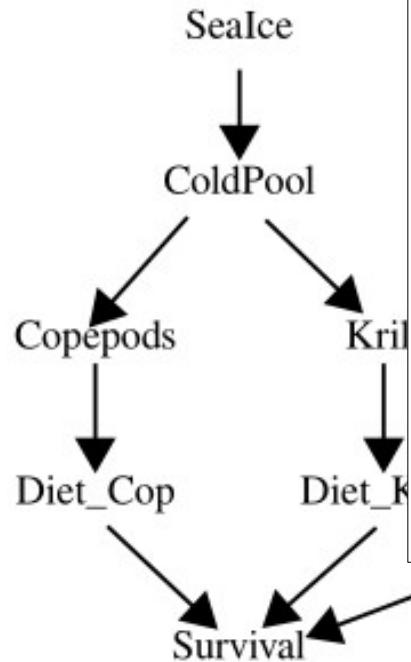


# ... expanded to handle missing data



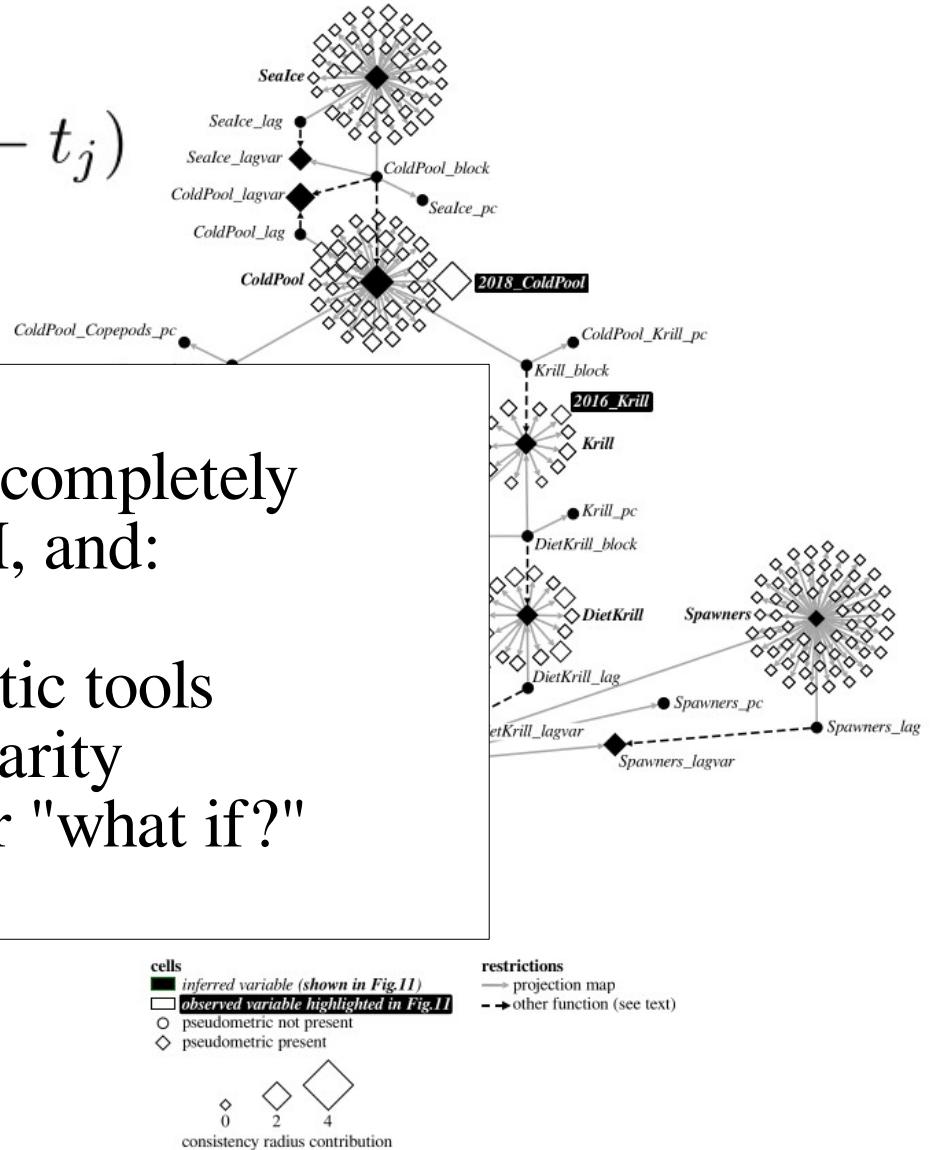
# Sheaves generalize DSEM

$$\frac{dx_k(\tau - t_\ell)}{d\tau} = \sum_{i=1}^J \sum_{j=1}^T \gamma_{k,\ell,i,j} x_i(\tau - t_j)$$



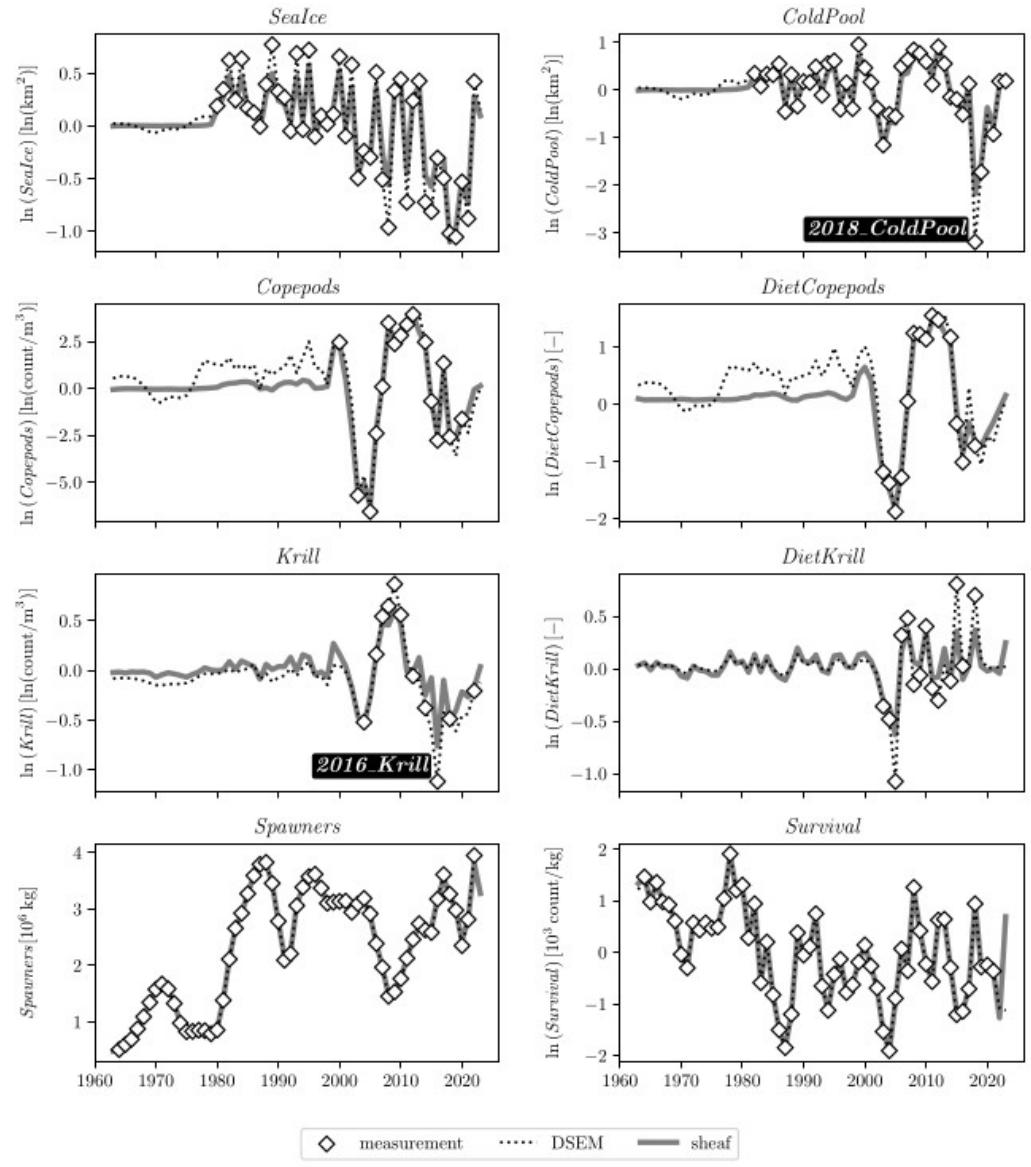
Theorem:  
The sheaf model completely recovers a DSEM, and:

- Adds new analytic tools
- Permits nonlinearity
- Supports deeper "what if?" exploration



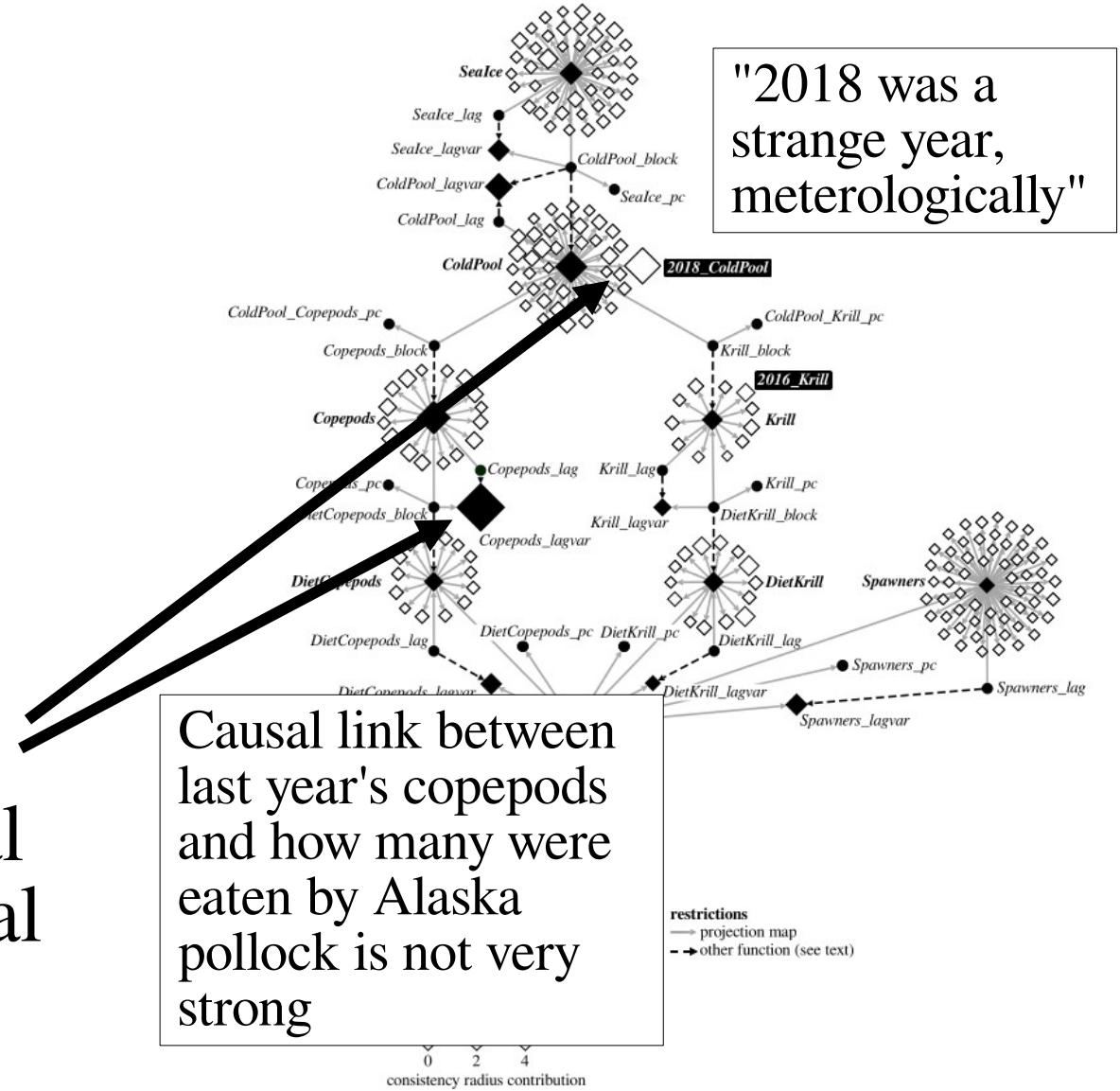
# The sheaf recovers the DSEM

- Missing data are imputed "maximum consistency" instead of "maximum likelihood"
- Path coefficients can be inferred in the same way
- Local consistency radius allows unusual observations to causal links to be detected



# The sheaf recovers the DSEM

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# Sheaf analytics: deeper math → better tools

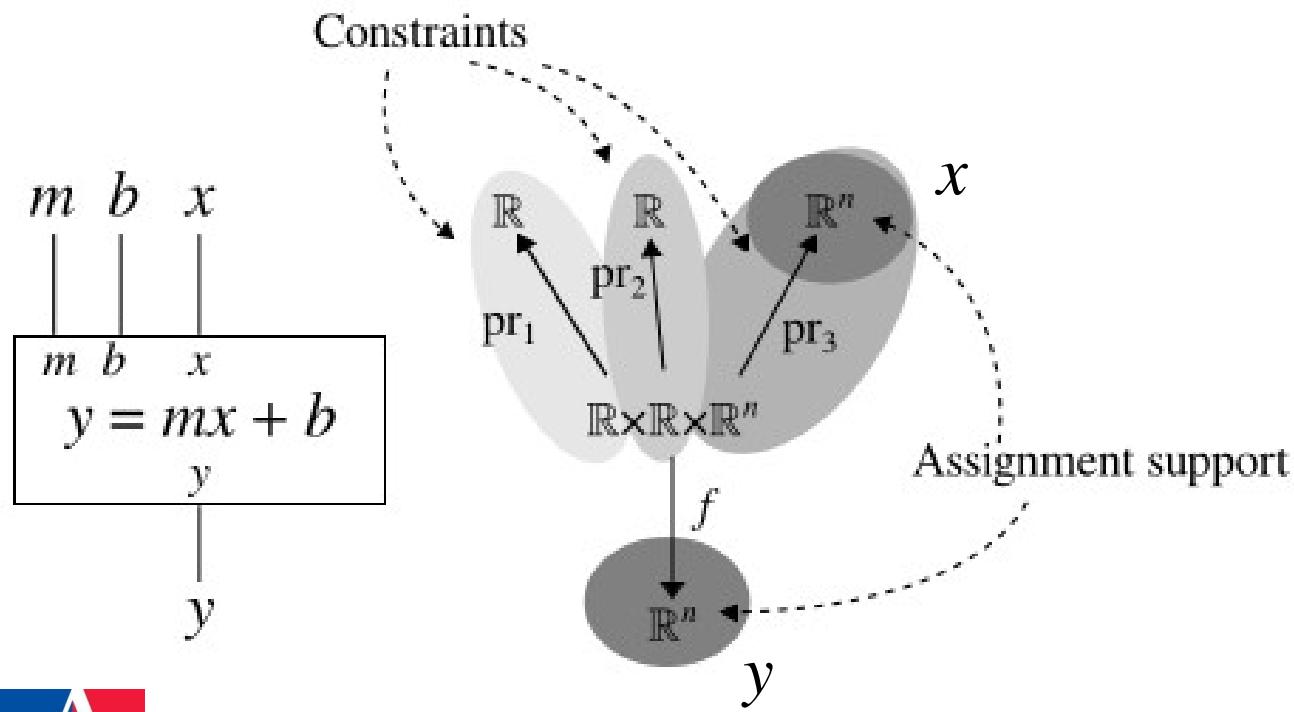


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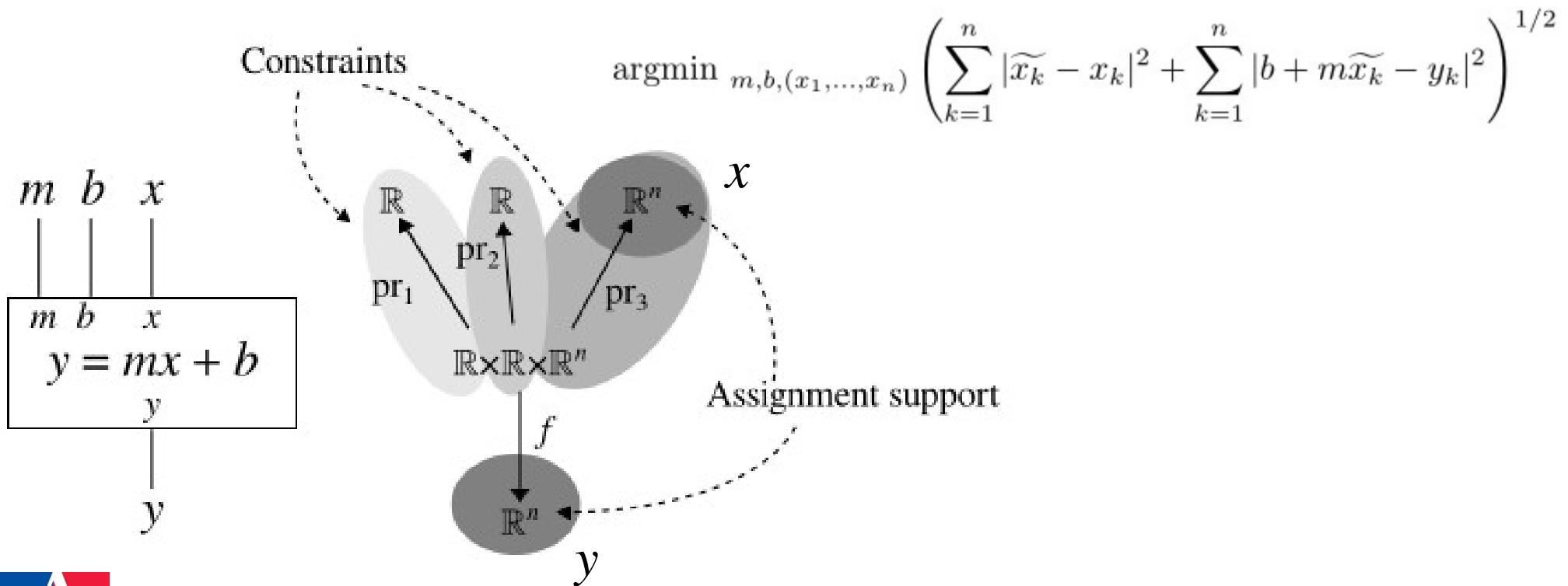
# Linear regression as a sheaf

- Put observations on  $x$  and  $y$  (the assignment support)
- Constraints ensure the copies of parameters in the sheaf all agree



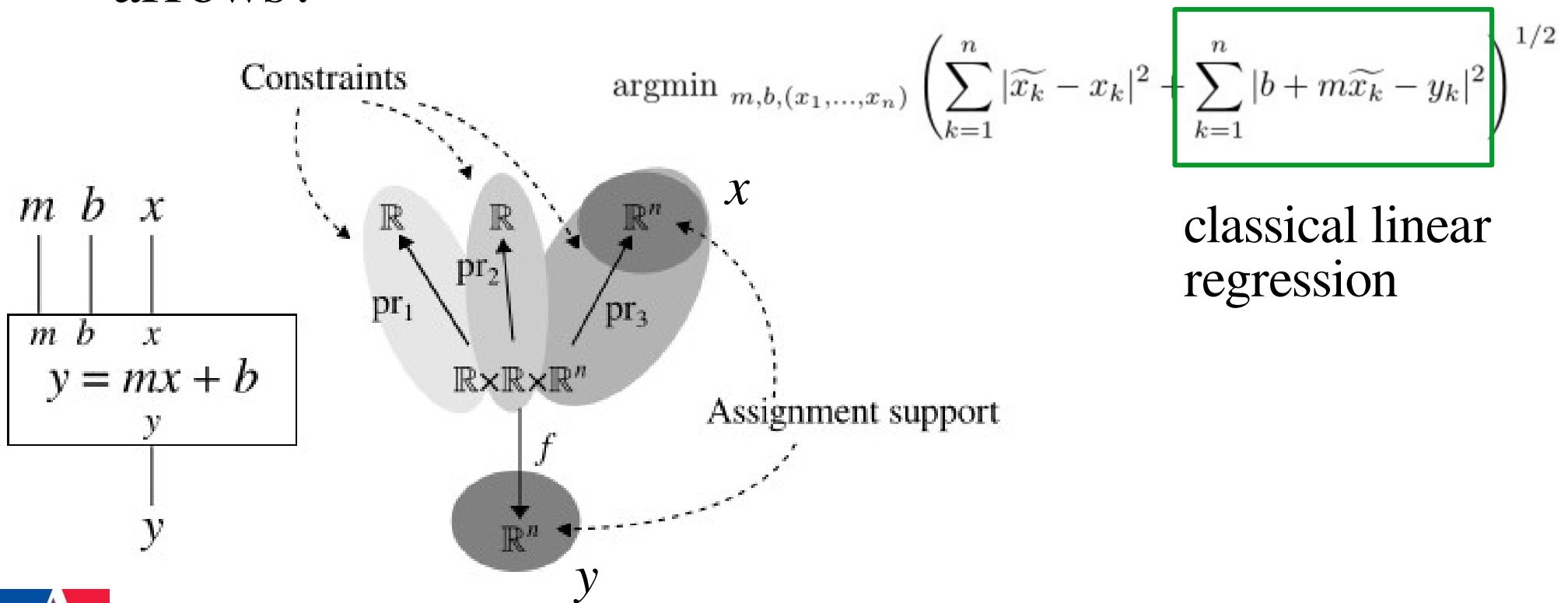
# Consistency radius

- Put observations on  $x$  and  $y$  (the assignment support)
- What values of  $m$  and  $b$  will yield the least disagreement when applying the functions on the arrows?



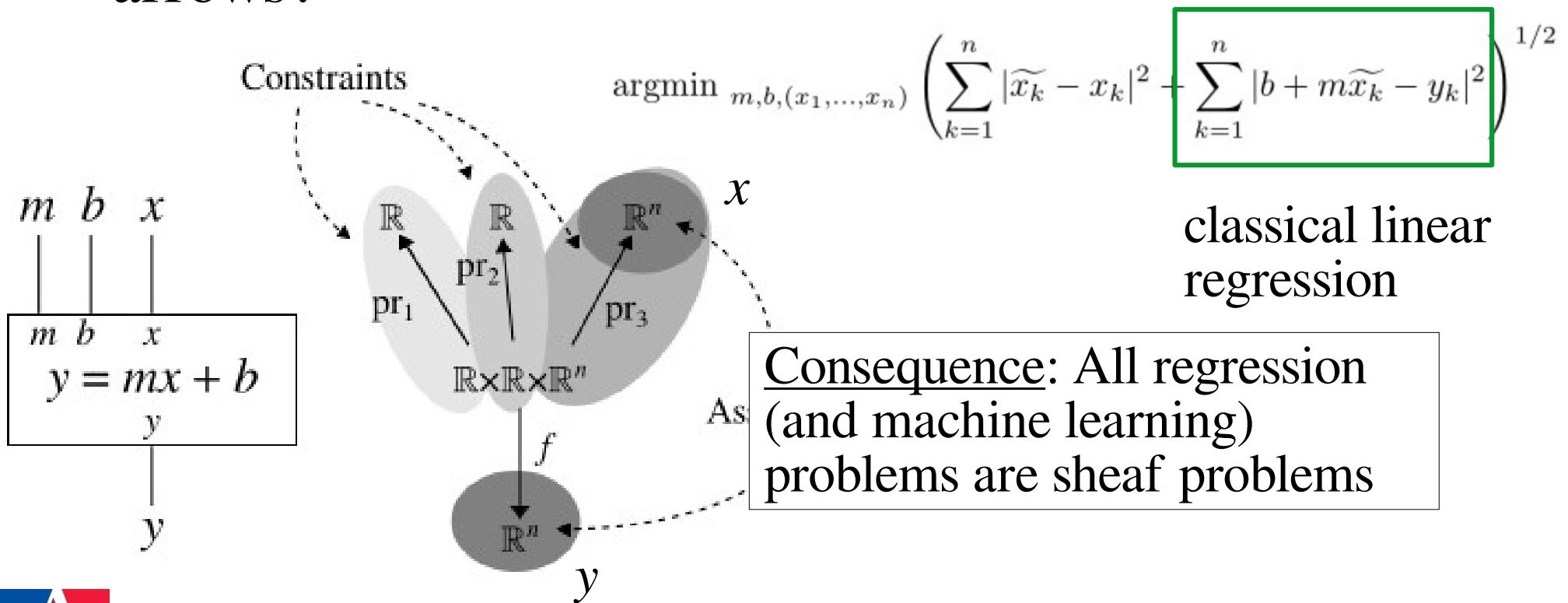
# Consistency radius

- Put observations on  $x$  and  $y$  (the assignment support)
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- Put observations on  $x$  and  $y$  (the assignment support)
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# Sheaf modeling discipline

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- A *sheaf* is a hypothesis about how a collection of variables interact
- An *assignment* is a sample of observations
- *Consistency radius* is a test statistic for the assignment being consistent with the sheaf
- *Minimizing consistency radius* estimates values of variables outside the sample



# Next steps

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- Goal: Estimate the distribution of consistency radii under mild assumptions
  - Payoff: Formal hypothesis testing using sheaves
- Goal: Leverage topological acoustics models (found last year by our team) into sheaves
  - Payoff: Topological filters attuned to the acoustic environment
  - Payoff: New geometric/topological features may be highly robust to uncertainty, allowing operation in challenging environments



# To learn more...

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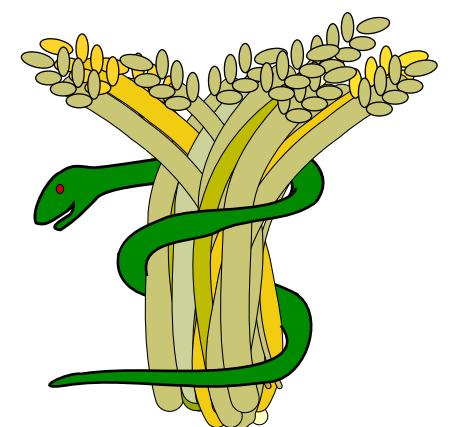
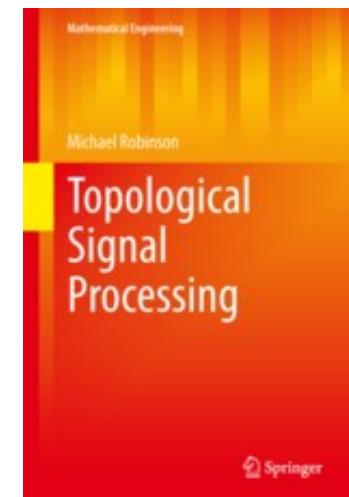
[michaelr@american.edu](mailto:michaelr@american.edu)

<http://drmichaelrobinson.net>

Relevant papers:

<https://arxiv.org/abs/2511.04603>

<https://doi.org/10.1111/2041-210X.14289>



Software:

<https://github.com/kb1dds>



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Michael Robinson