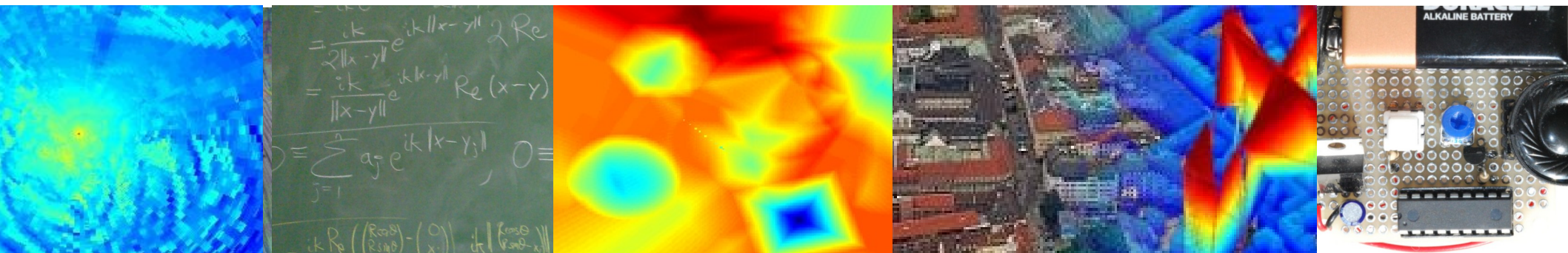


Topological Features *into* Complex Models



Michael Robinson



Acknowledgments

- Students:
 - Zander Memon (AU)
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 - Michael Postol
 - Michael Szulczewski (MITRE)
 - James Thorson (NOAA)
- Funding: Jason Chaytor (ONR) and PNNL KBASE
- Main references:

<https://arxiv.org/abs/2511.04603>

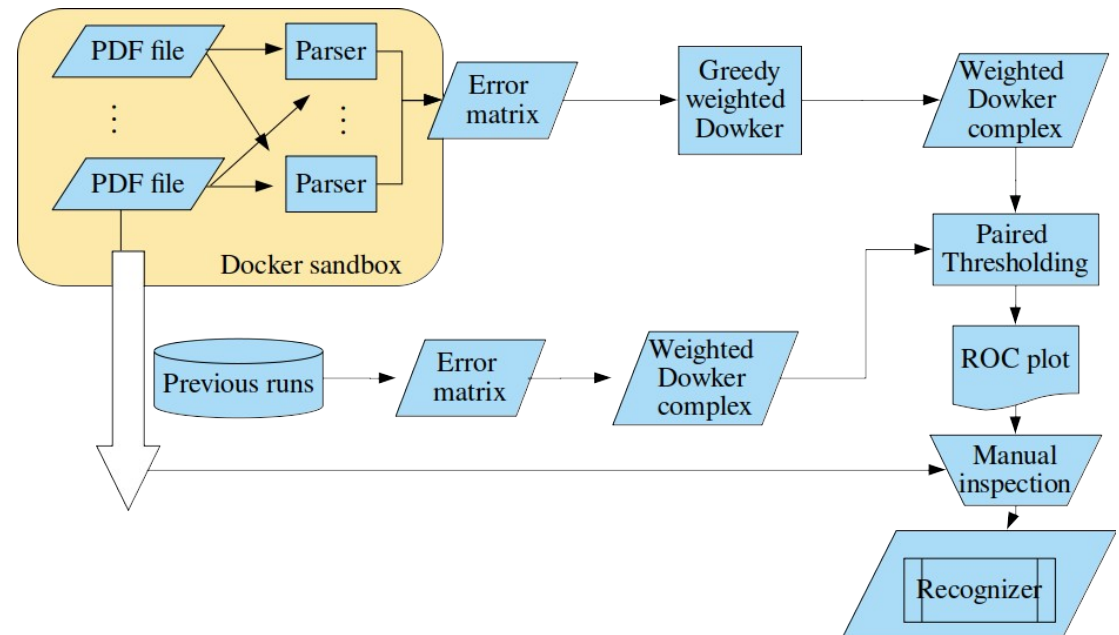
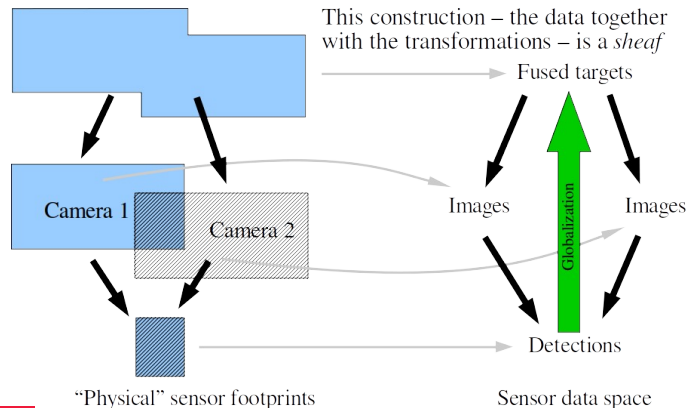
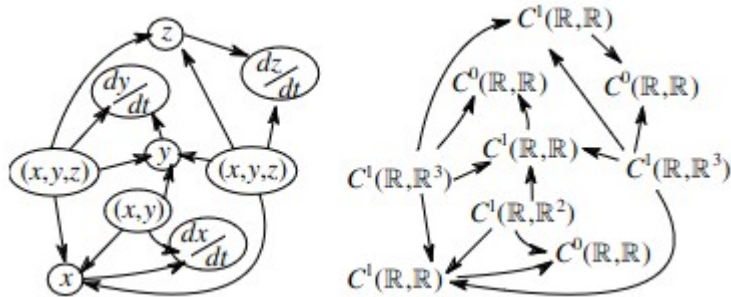
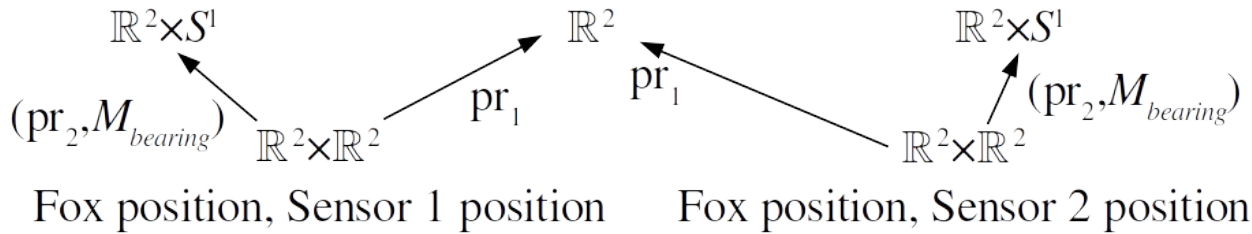
<https://github.com/kb1dds/netlist-sheaf>

Thorson, J. T., Andrews, A. G., Essington, T., & Large, S. (2024). Dynamic structural equation models synthesize ecosystem dynamics constrained by ecological mechanisms. *Methods in Ecology and Evolution* 15(4): 744-755. <https://doi.org/10.1111/2041-210X.14289>



Systems of systems are diagrams...

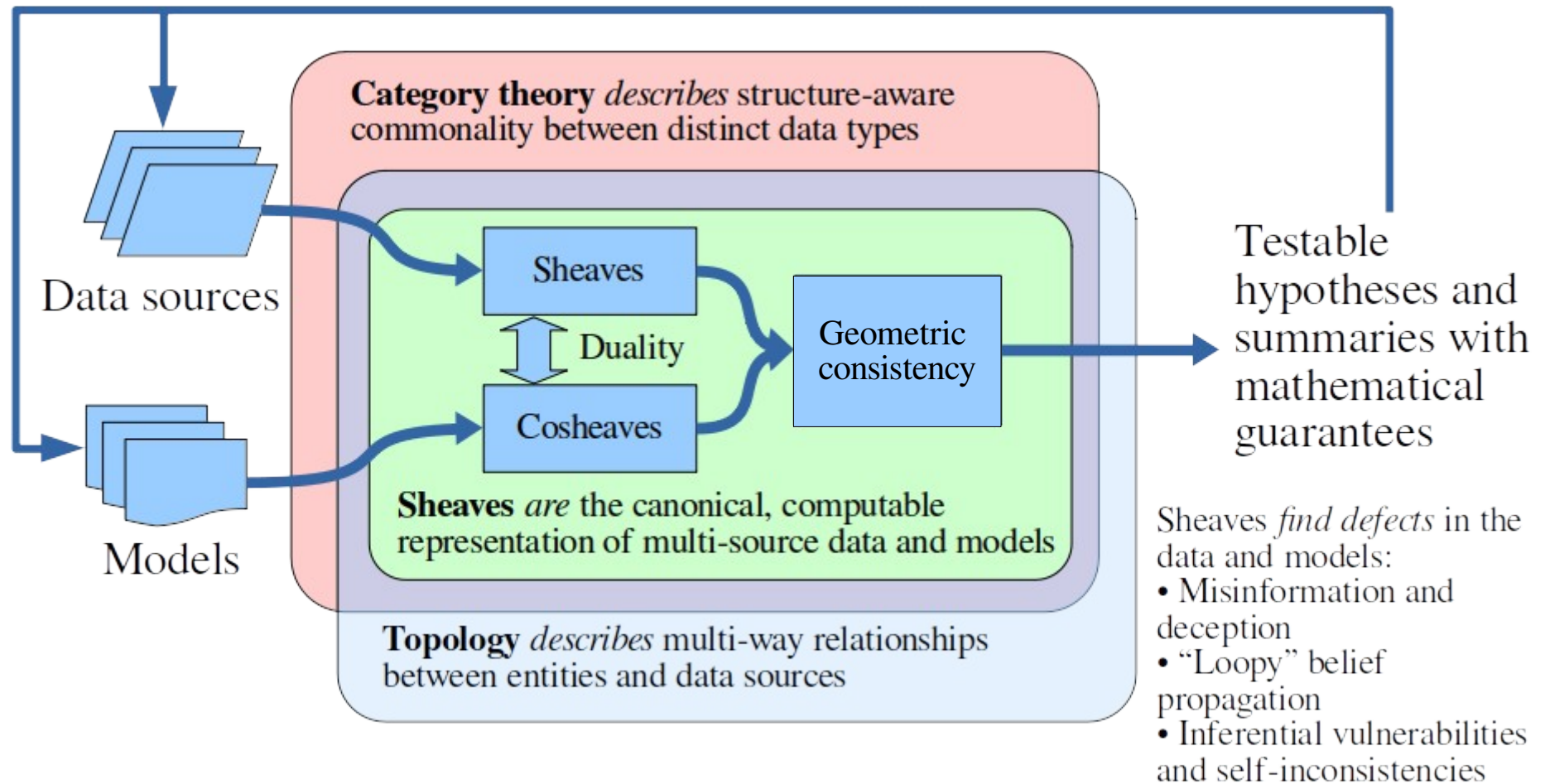
Sensor 1 position, Bearing Fox position Sensor 2 position, Bearing



... so use mathematics suited to diagrams:
topology, sheaves, and categories

... and the correct mathematical tools yield performance guarantees

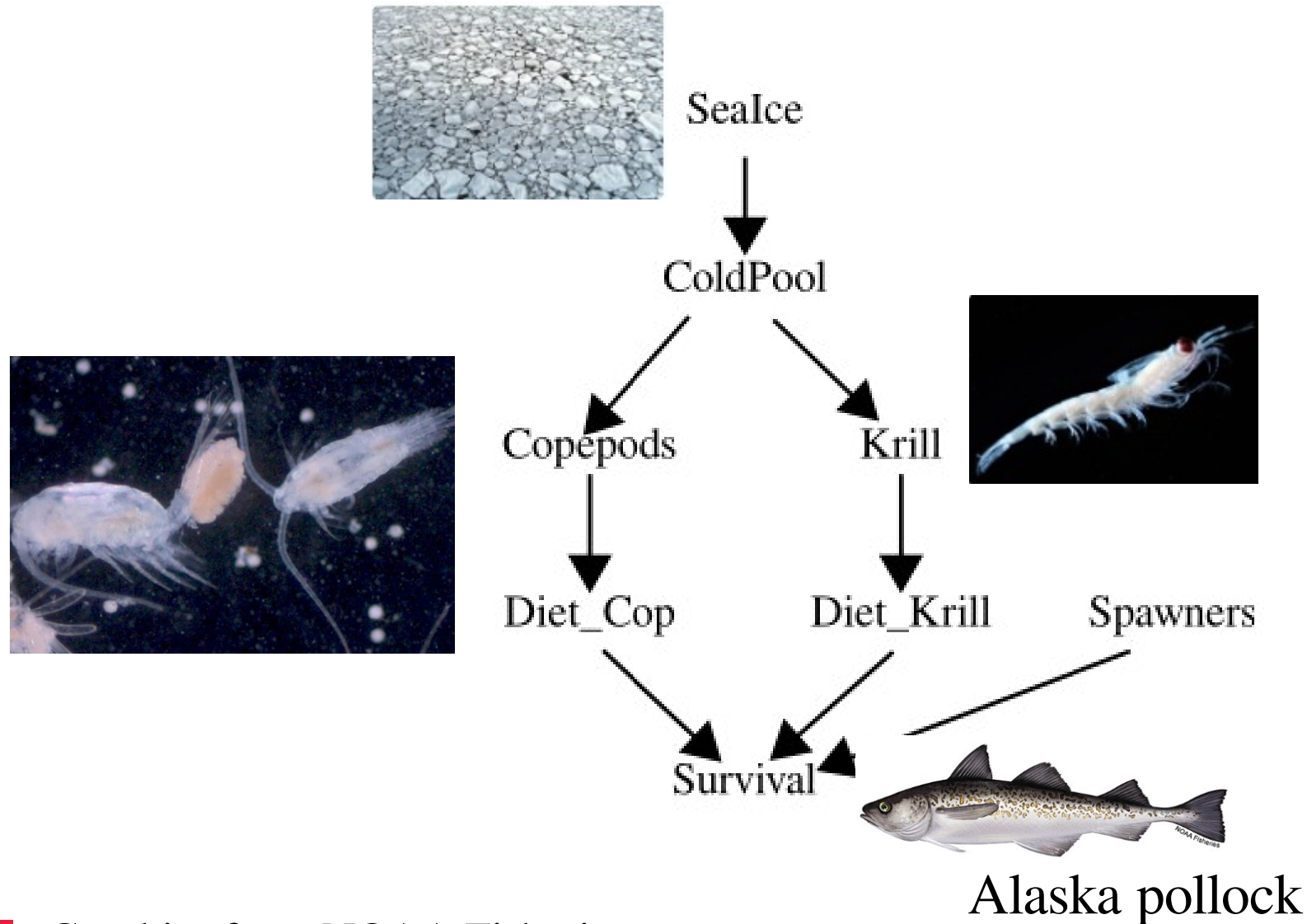
Sheaf-based tools *close the loop* on data science



Translating models into sheaves



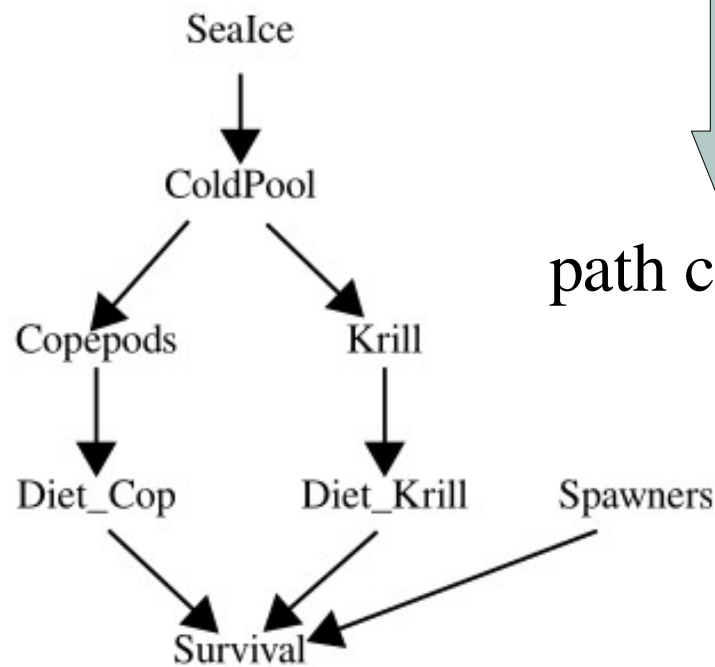
Dynamic Structural Equation Model



Graphics from NOAA Fisheries

Dynamic Structural Equation Model

$$\frac{dx_k(\tau - t_\ell)}{d\tau} = \sum_{i=1}^J \sum_{j=1}^T \gamma_{k,\ell,i,j} x_i(\tau - t_j)$$



Time lags t_j not shown

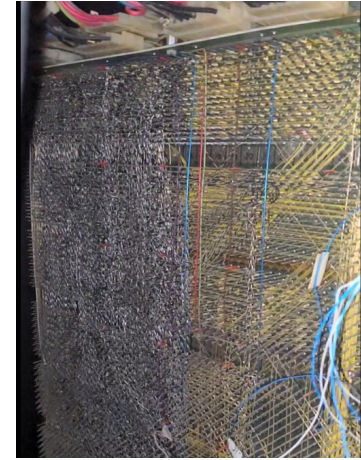
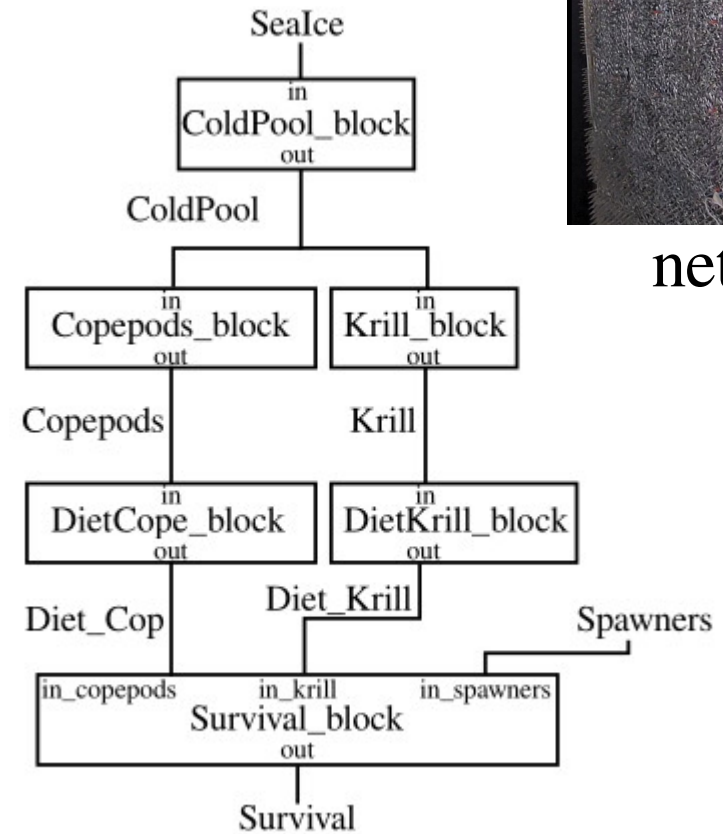
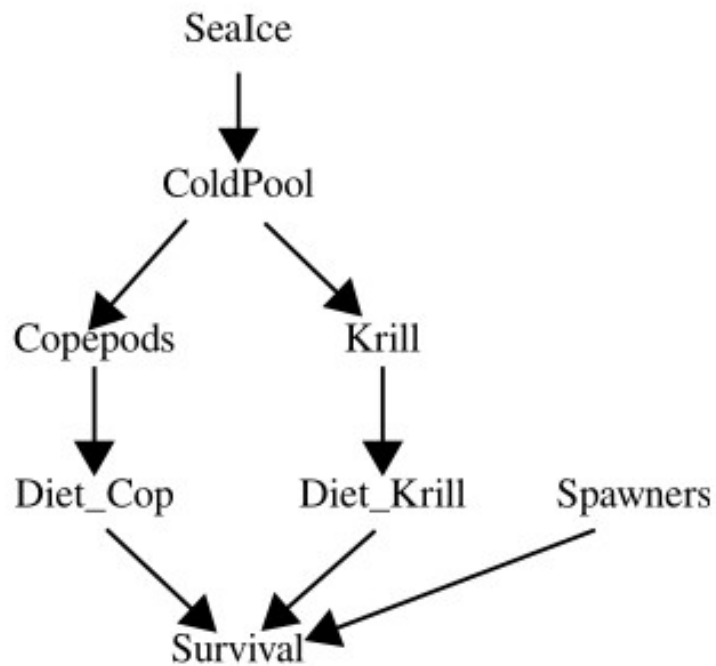
variables x_i are nodes

path coefficients γ are directed edges



DSEM → netlist (circuit diagram)

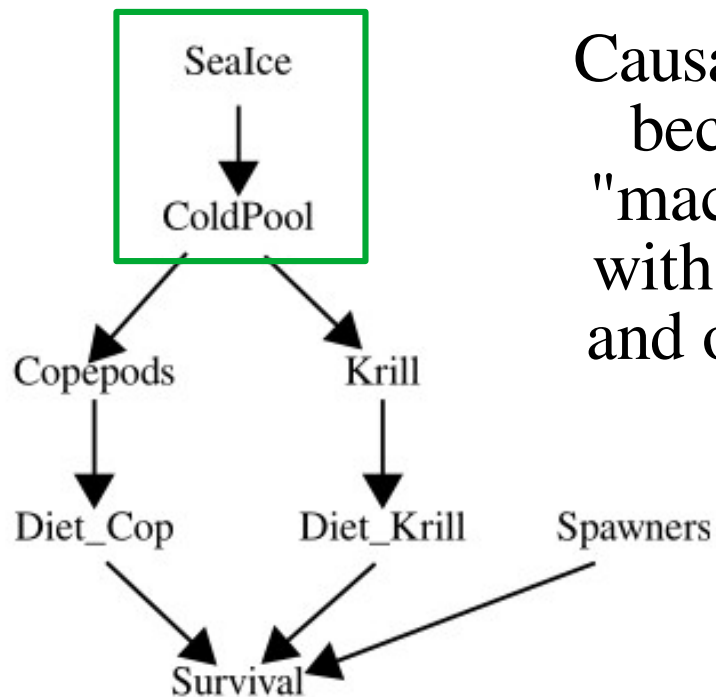
$$\frac{dx_k(\tau - t_\ell)}{d\tau} = \sum_{i=1}^J \sum_{j=1}^T \gamma_{k,\ell,i,j} x_i(\tau - t_j)$$



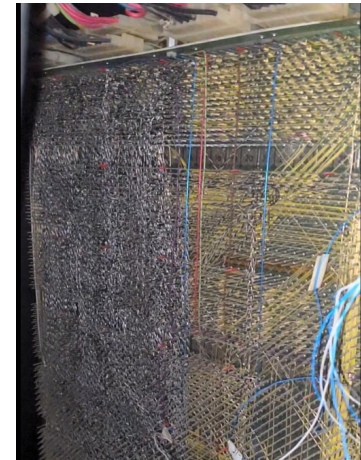
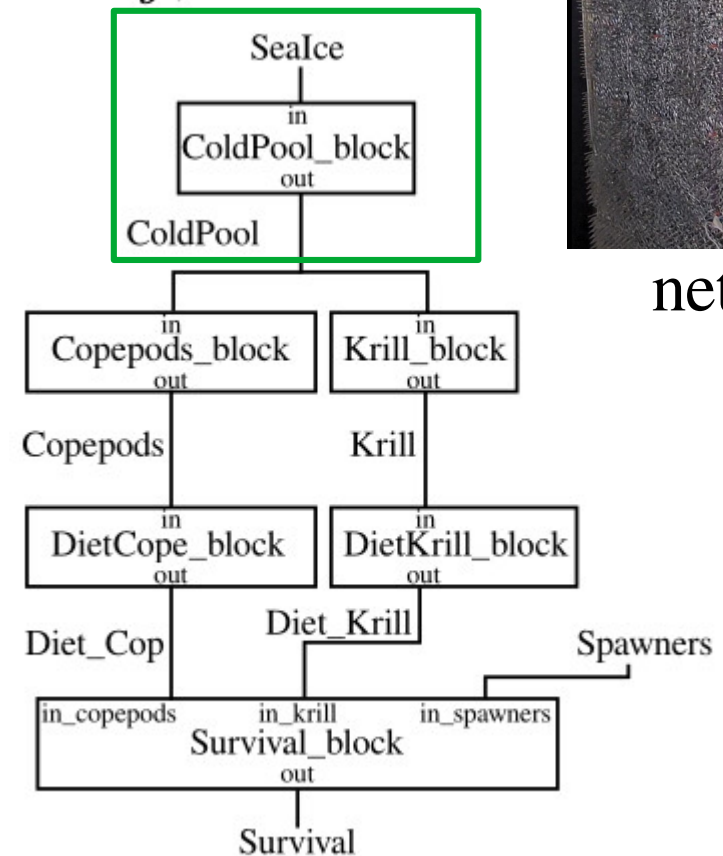
netlists!

DSEM → netlist (circuit diagram)

$$\frac{dx_k(\tau - t_\ell)}{d\tau} = \sum_{i=1}^J \sum_{j=1}^T \gamma_{k,\ell,i,j} x_i(\tau - t_j)$$

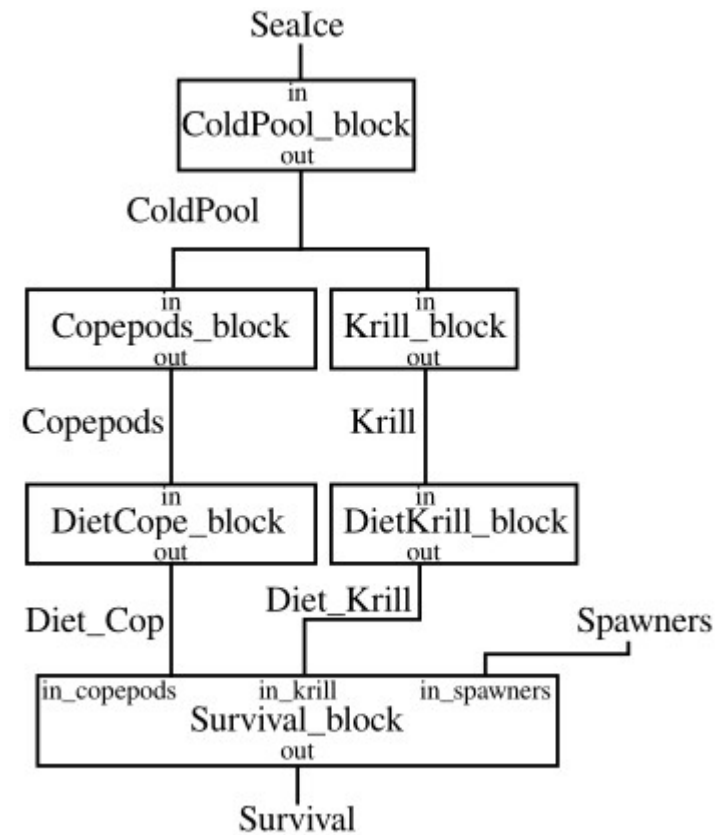
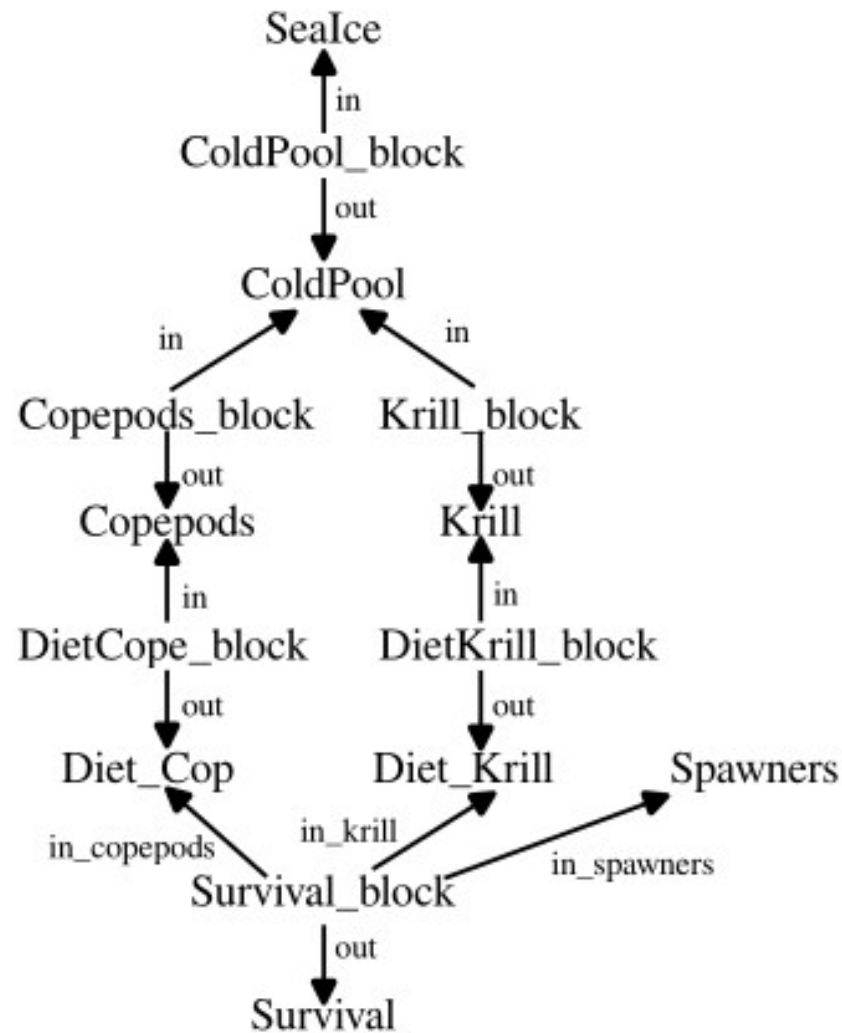


Causal paths
become
"machines"
with inputs
and outputs

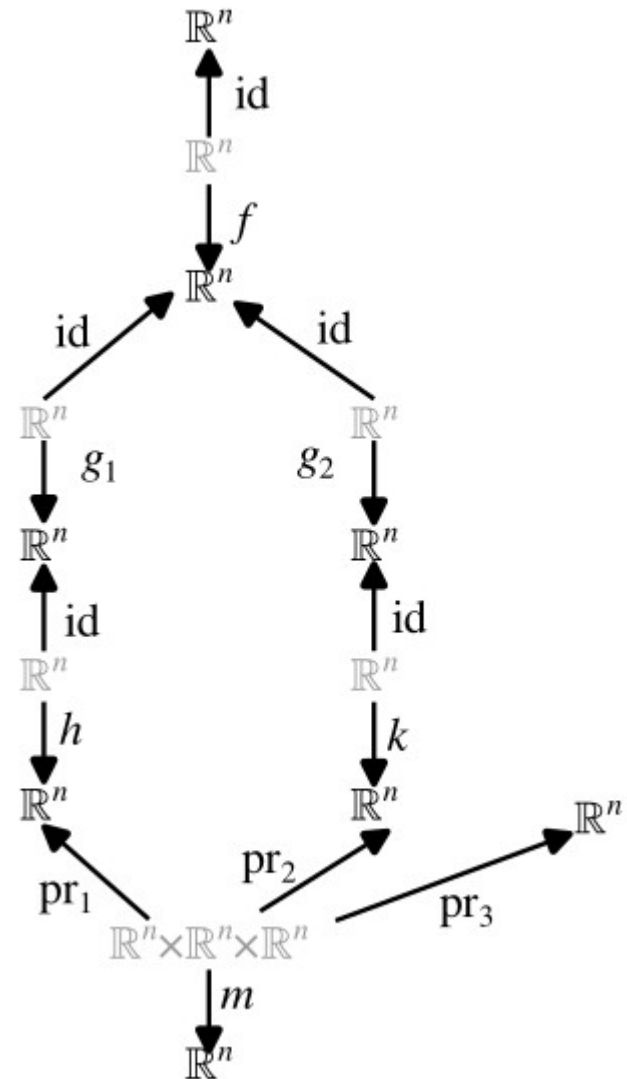
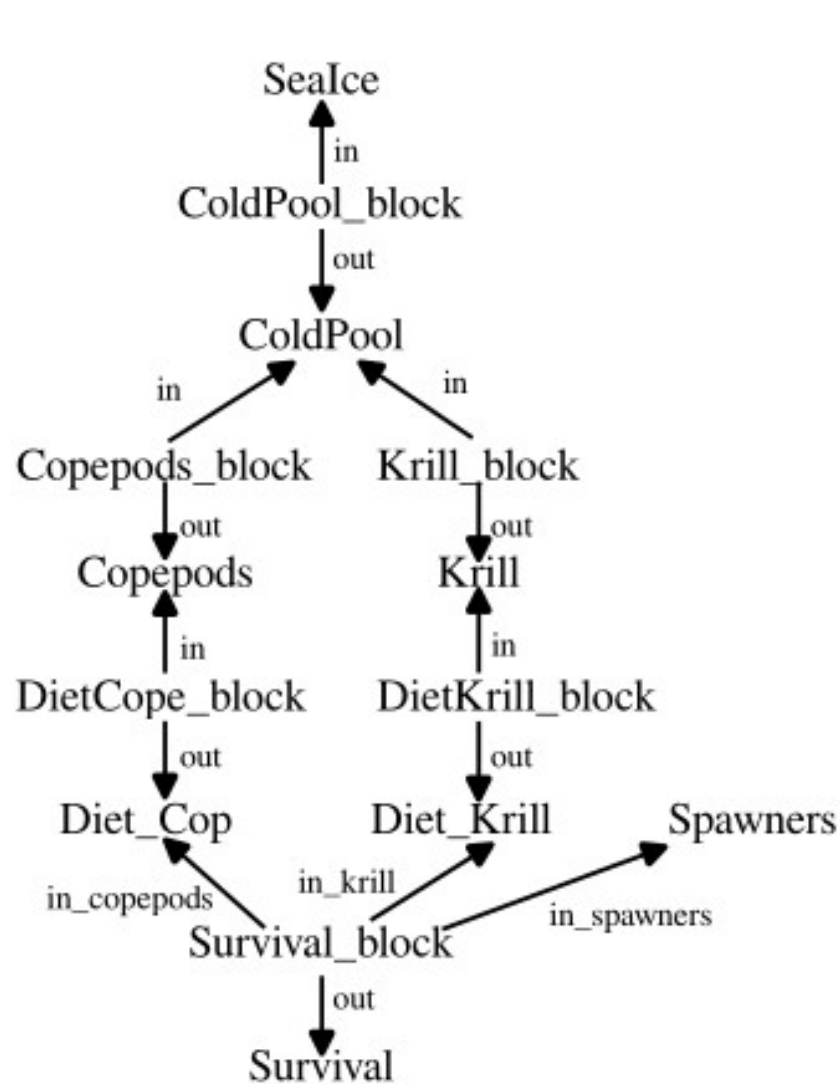


netlists!

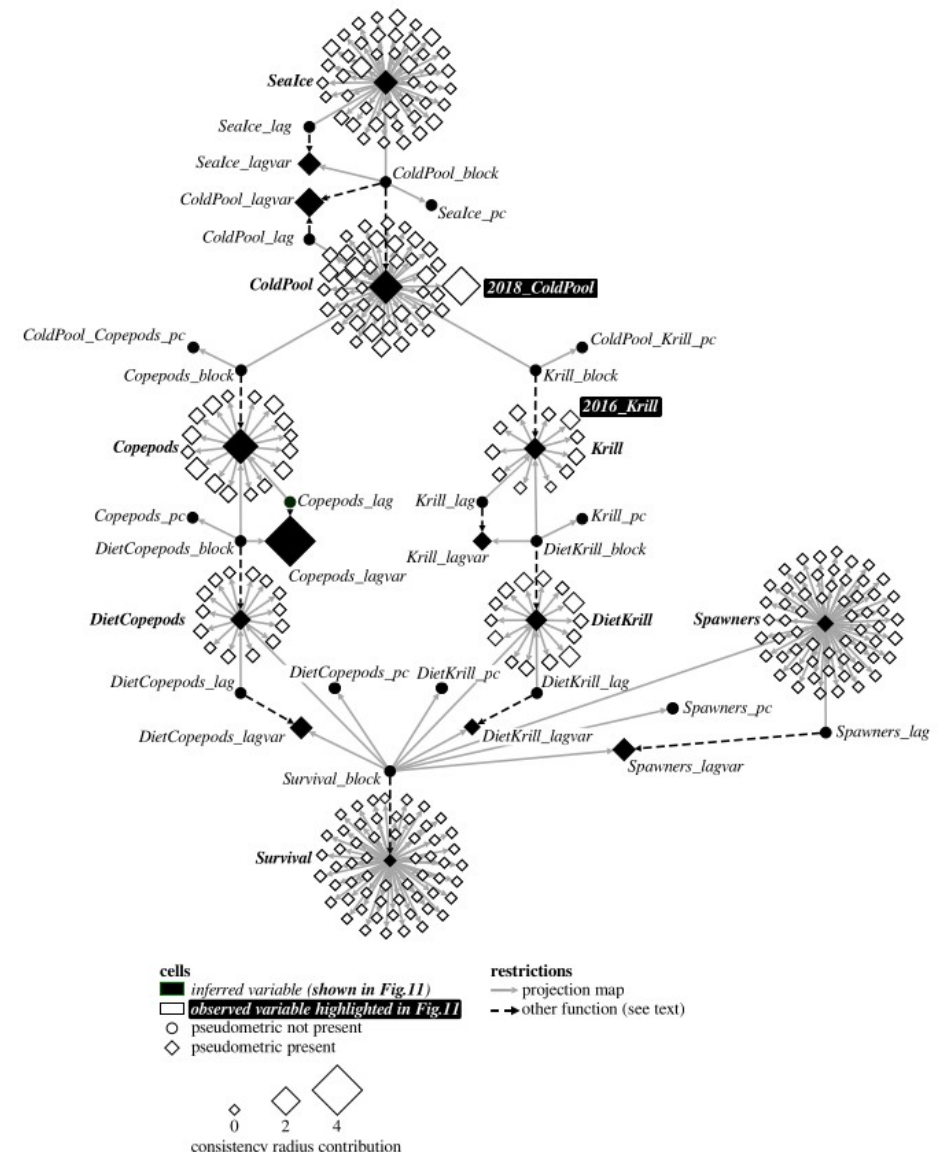
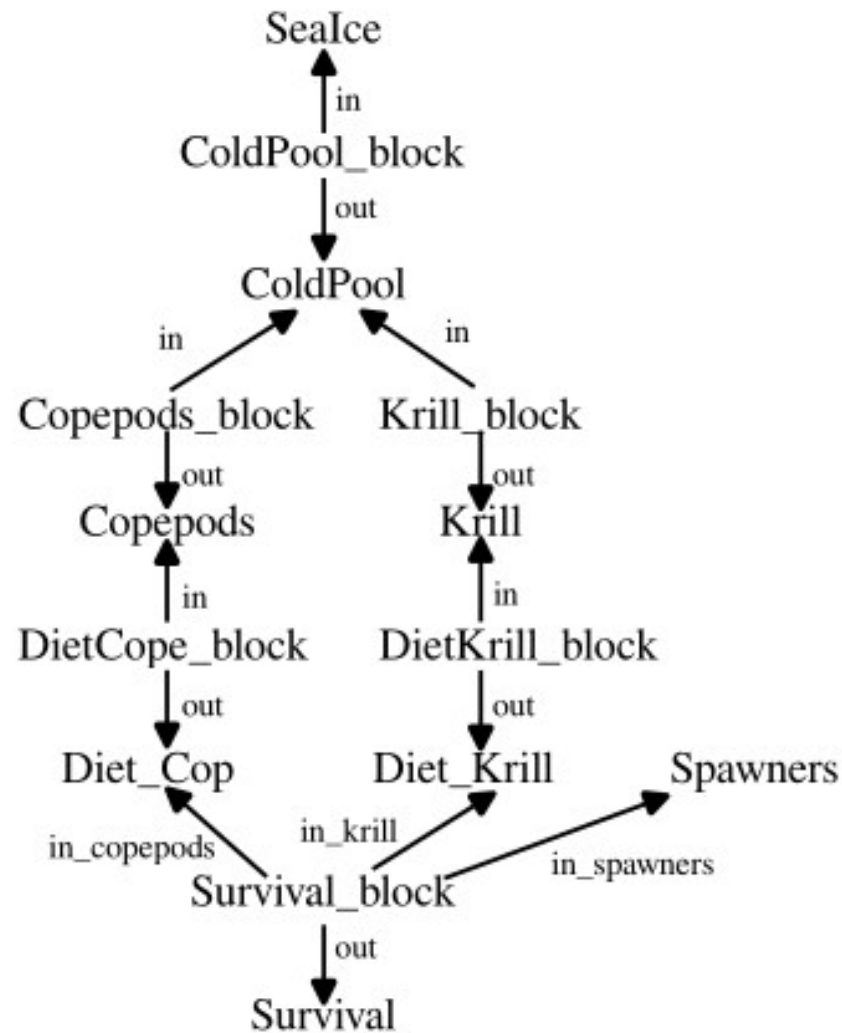
Netlist incidence graph



Incidence graph to sheaf

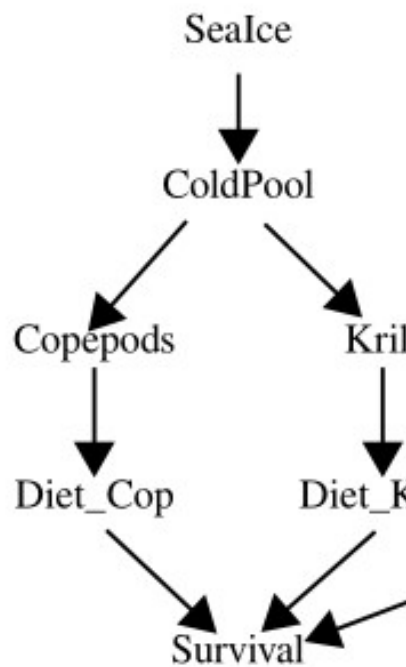


... expanded to handle missing data



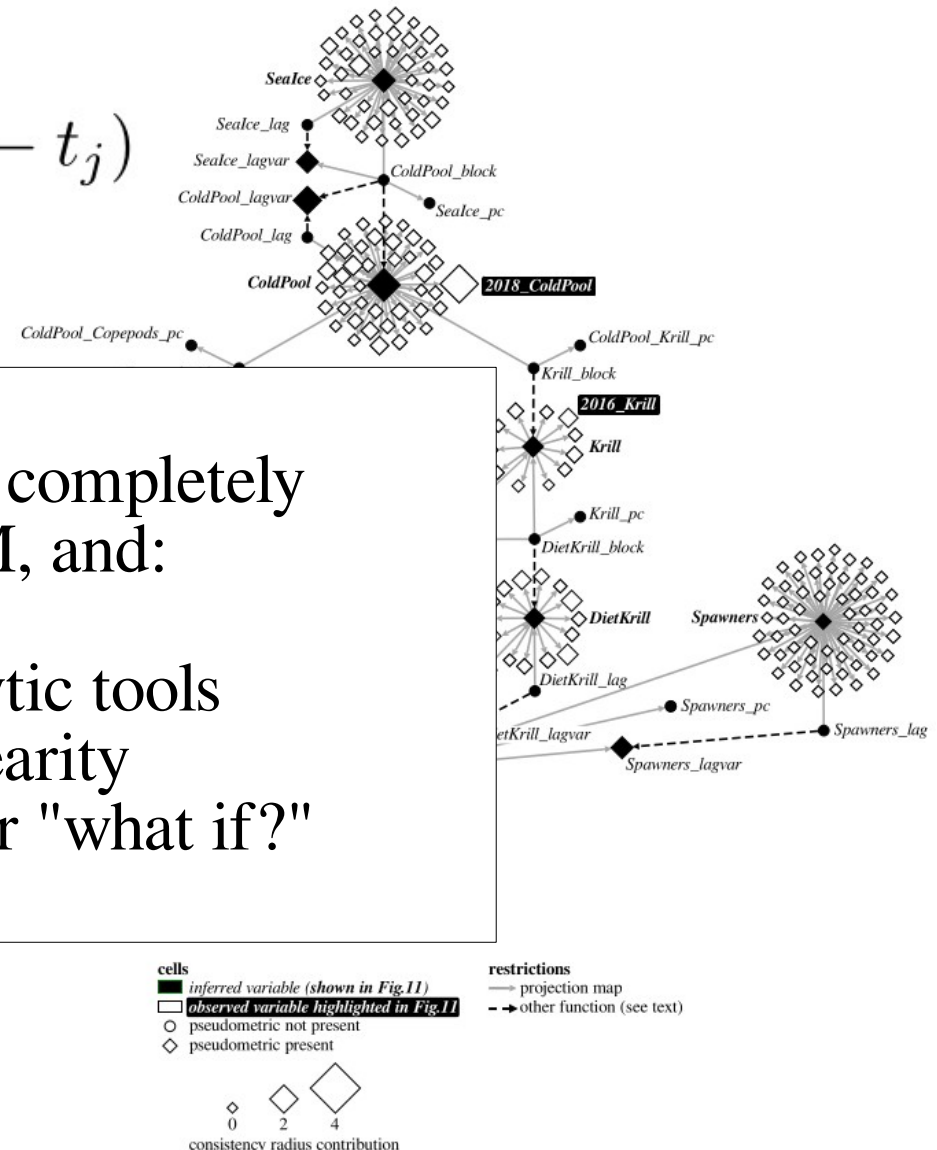
Sheaves generalize DSEM

$$\frac{dx_k(\tau - t_\ell)}{d\tau} = \sum_{i=1}^J \sum_{j=1}^T \gamma_{k,\ell,i,j} x_i(\tau - t_j)$$



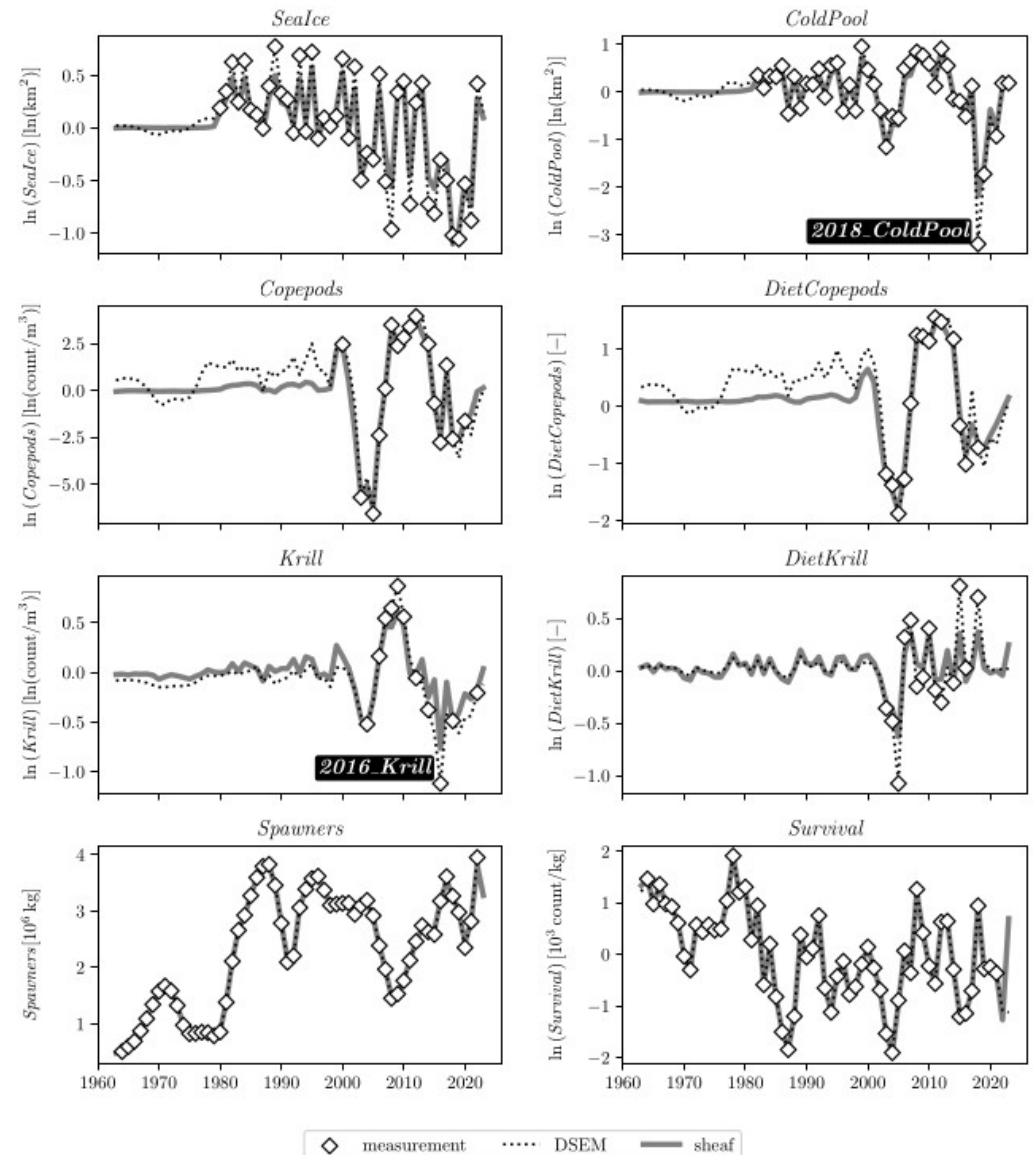
Theorem:
The sheaf model completely recovers a DSEM, and:

- Adds new analytic tools
- Permits nonlinearity
- Supports deeper "what if?" exploration



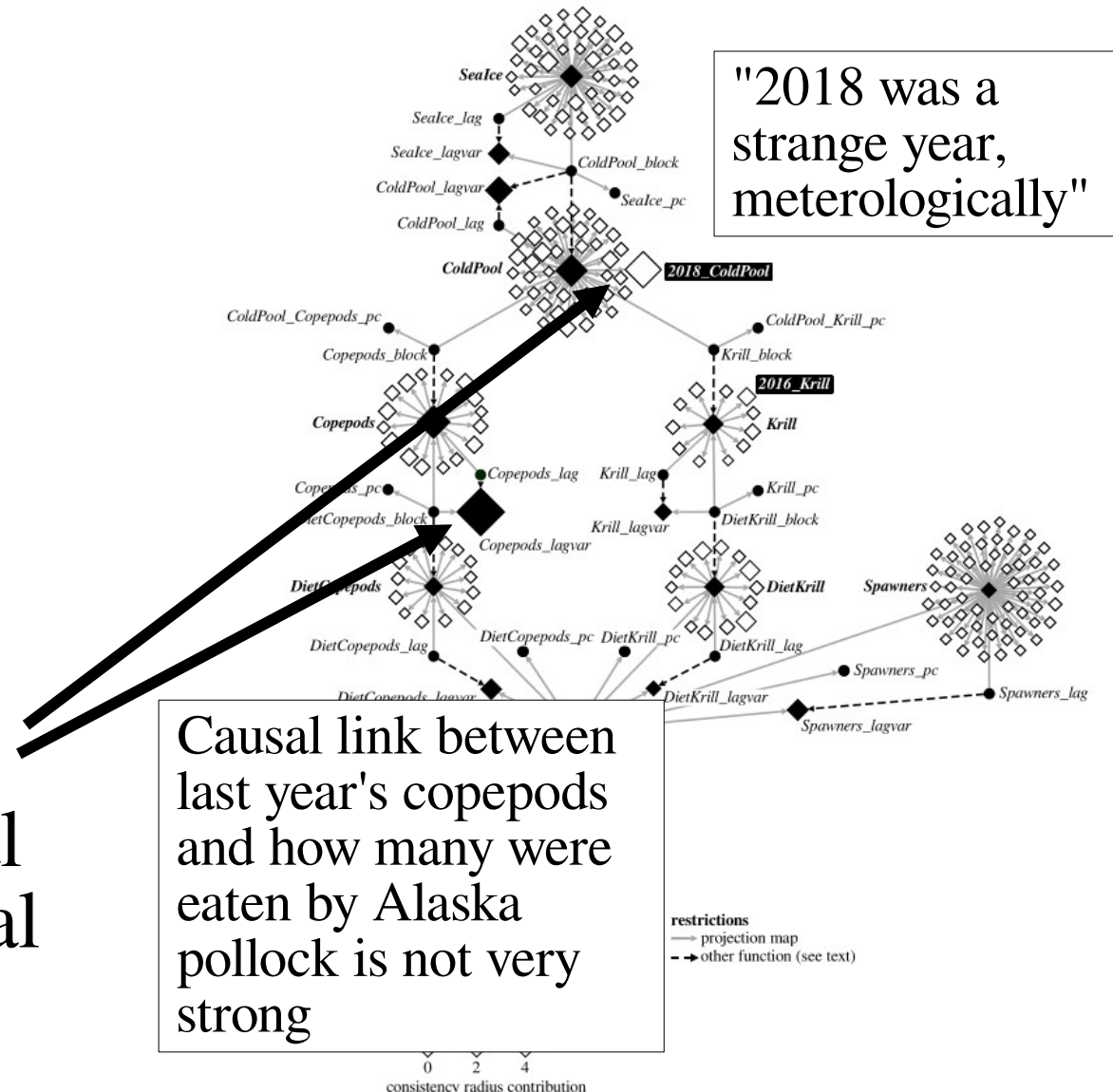
The sheaf recovers the DSEM

- Missing data are imputed "maximum consistency" instead of "maximum likelihood"
- Path coefficients can be inferred in the same way
- Local consistency radius allows unusual observations to causal links to be detected



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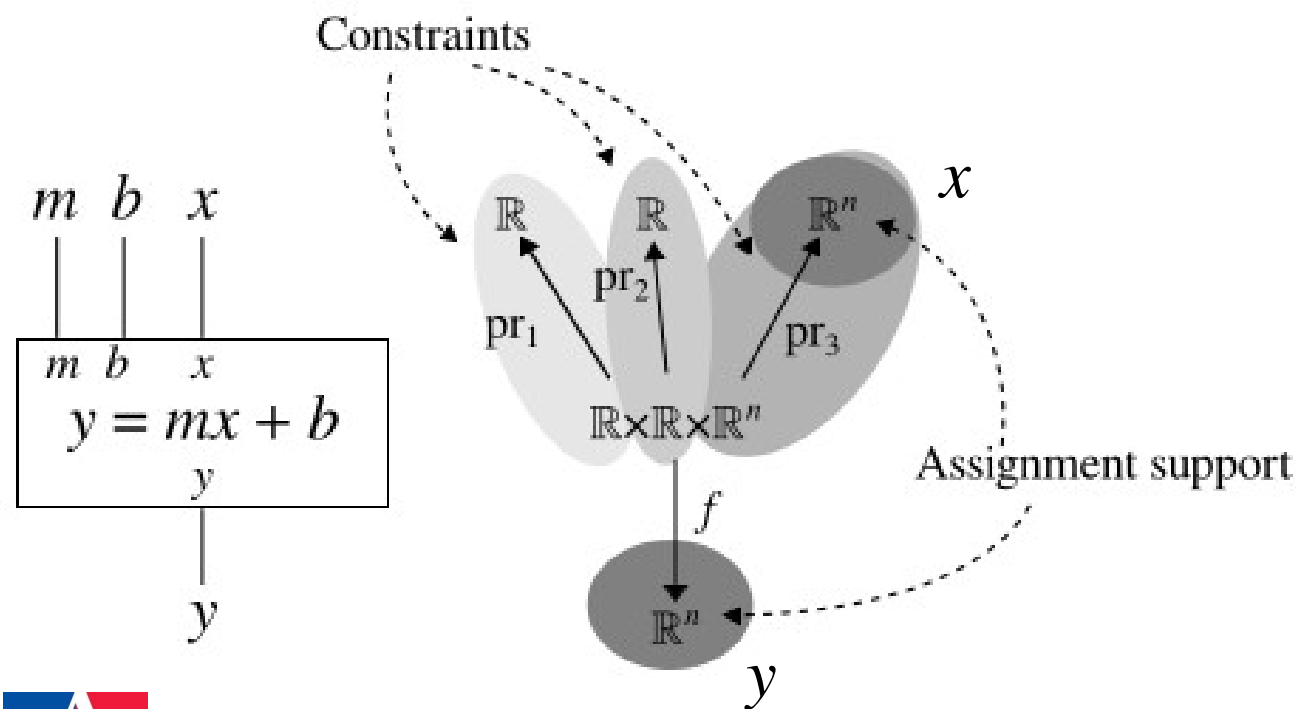


Sheaf analytics:
deeper math \rightarrow better tools



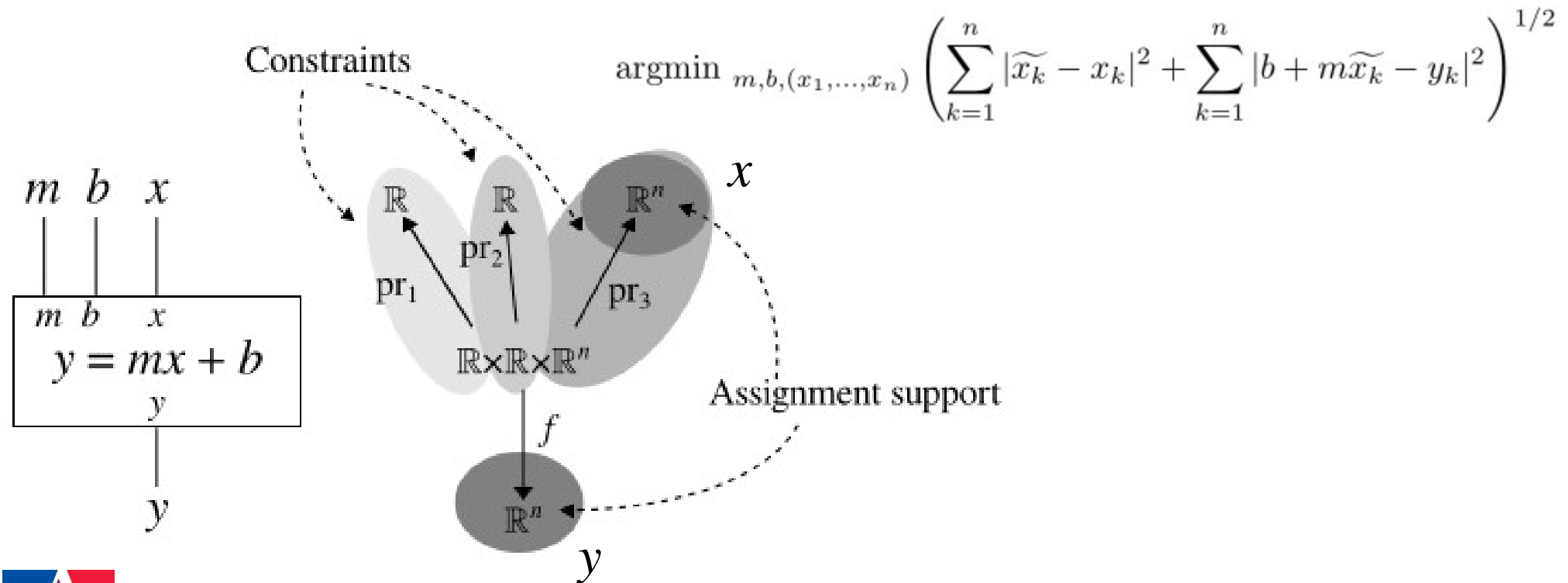
Linear regression as a sheaf

- Put observations on x and y (the assignment support)
- Constraints ensure the copies of parameters in the sheaf all agree



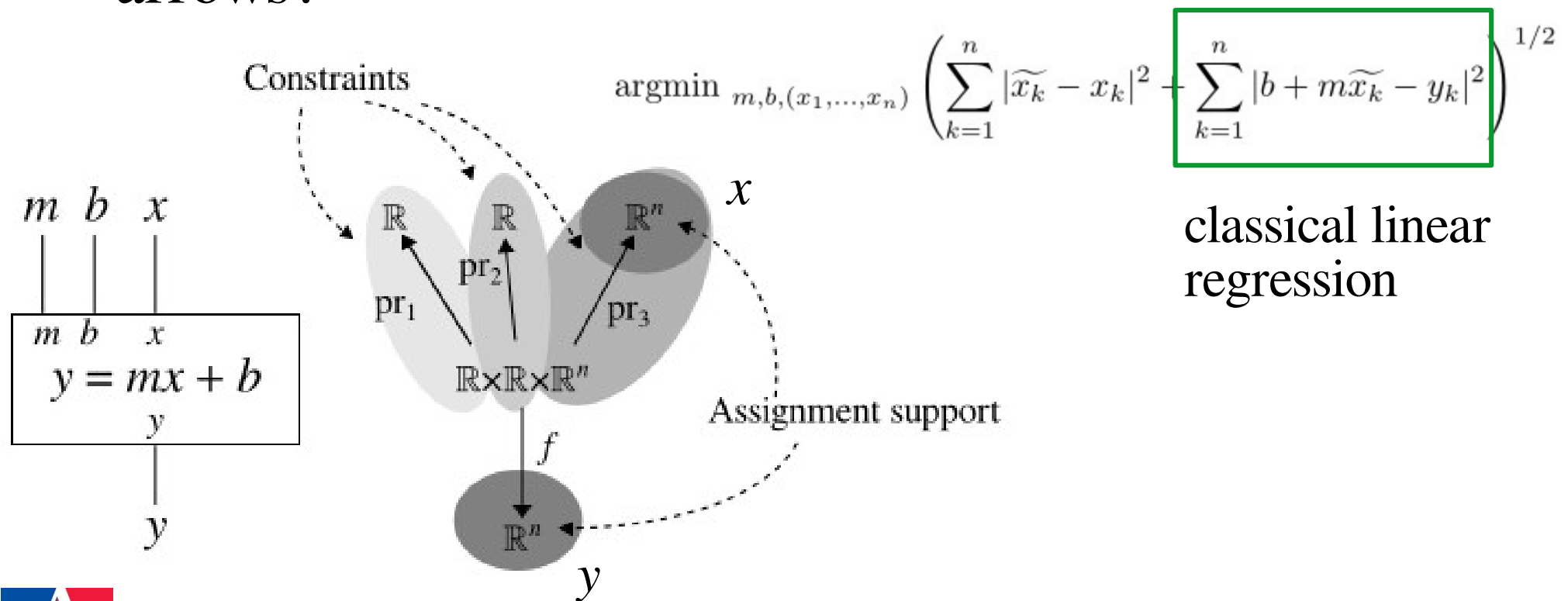
Consistency radius

- Put observations on x and y (the assignment support)
- What values of m and b will yield the least disagreement when applying the functions on the arrows?



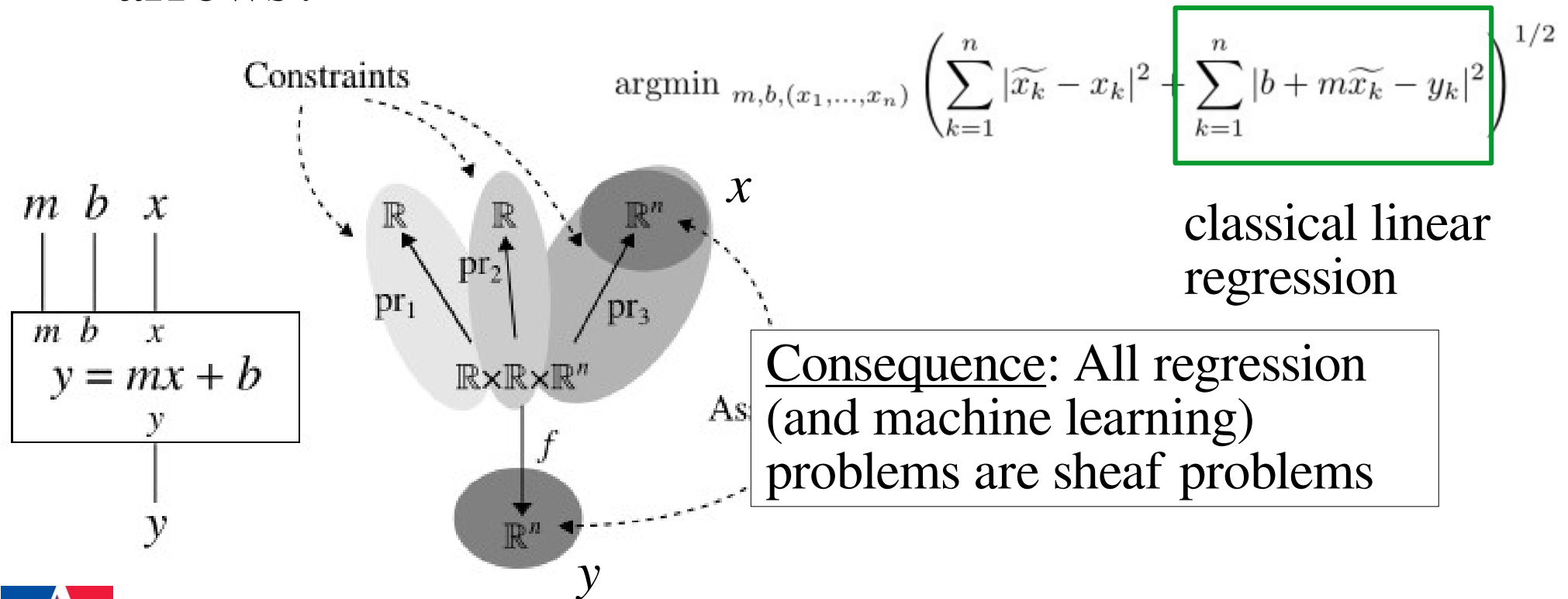
Consistency radius

- Put observations on x and y (the assignment support)
- What values of m and b will yield the least disagreement when applying the functions on the arrows?



Consistency radius

- Put observations on x and y (the assignment support)
- What values of m and b will yield the least disagreement when applying the functions on the arrows?



Sheaf modeling discipline

- **A *sheaf* is a hypothesis** about how a collection of variables interact
- **An *assignment* is a sample** of observations
- ***Consistency radius* is a test statistic** for the assignment being consistent with the sheaf
- ***Minimizing consistency radius* estimates values** of variables outside the sample



Next steps

- Goal: Estimate the distribution of consistency radii under mild assumptions
 - Payoff: Formal hypothesis testing using sheaves
- Goal: Leverage topological acoustics models (found last year by our team) into sheaves
 - Payoff: Topological filters attuned to the acoustic environment
 - Payoff: New geometric/topological features may be highly robust to uncertainty, allowing operation in challenging environments



To learn more...

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<http://drmichaelrobinson.net>

Relevant papers:

<https://arxiv.org/abs/2511.04603>

<https://doi.org/10.1111/2041-210X.14289>

Software:

<https://github.com/kb1dds>

